SUPER •

SUPER X6DA8-G SUPER X6DAE-G SUPER X6DA8-G2 SUPER X6DAE-G2

USER'S MANUAL

Revision 1.0c

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Preface

About This Manual

This manual is written for system integrators, PC technicians and knowledgeable PC users. It provides information for the installation and use of the SUPER● X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2 motherboard. The SUPER® X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2 supports single or dual Intel® Xeon Nocona™ processors at a 800 MHz front side bus. upon Intel's NetBurst microarchitecture with EM64T support, the Nocona processor supports the IA-32 software and includes features found in the Xeon[™] processor such as Hyper Pipelined Technology, which includes a multi-stage pipeline, allowing the processor to operate at much higher core frequencies. Packaged in a 604-pin Flip Chip Micro Pin Grid Array(FCmPGA4) platform in a Zero Insertion Force(ZIF) socket (mPGA 604), the Nocona Processor (800 MHz) supports Hyper-Threading Technology and is ideal for high performance workstation and server environments with up to two processors on one system bus. Please refer to the motherboard specifications pages on our web site (http://www.supermicro.com/ Product_page/product-m.htm) for updates on supported processors. This product is intended to be professionally installed.

Manual Organization

Chapter 1 begins with a checklist of what should be included in your mainboard box, describes the features, specifications and performance of the motherboard and provides detailed information about the chipset.

Chapter 2 begins with instructions on handling static-sensitive devices. Read this chapter when you want to install the processor and DIMM memory modules and when mounting the mainboard in the chassis. Also refer to this chapter to connect the floppy and hard disk drives, SCSI drives, the IDE interfaces, the parallel and serial ports, the keyboard and mouse, the power supply and various control panel buttons and indicators.

If you encounter any problems, see **Chapter 3**, which describes trouble-shooting procedures for the video, the memory and the setup configuration stored in CMOS. For quick reference, a general FAQ [Frequently Asked Questions] section is provided.

Chapter 4 includes an introduction to BIOS and provides detailed information on running the CMOS Setup utility.

Appendix A gives information on BIOS POST messages.

Appendix B provides software and the OS installation instructions.

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Chapter 1 Introduction

1-1 Overview

Checklist

Congratulations on purchasing your computer motherboard from an acknowledged leader in the industry. Supermicro boards are designed with the utmost attention to detail to provide you with the highest standards in quality and performance. Check that the following items have all been included with your motherboard. If anything listed here is damaged or missing, contact your retailer. All included with Retail Box.

- One (1) Supermicro Mainboard
- One (1) ribbon cable for IDE devices
- One (1) floppy ribbon cable
- One (1) SCSI-U320 cable (*X6DA8-G/X6DA8-G2)
- One (1) SATA cable
- One (1) I/O backpanel shield
- One (1) Supermicro CD containing drivers and utilities
- One (1) User's/BIOS Manual
- One (1) SCSI User's Manual (*X6DA8-G/X6DA8-G2)
- Two (2) CPU Mounting Brackets (SKT-0158) (pre-installed)

Contacting Supermicro

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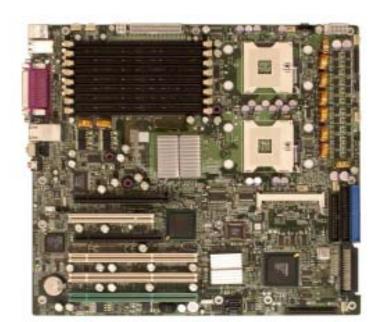


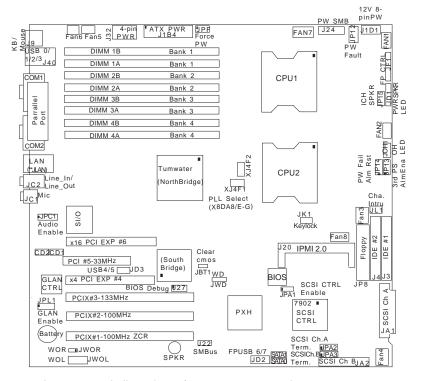
Figure 1-1. SUPER X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2 Image

*Notes: The differences between these models are:

- 1.SCSI is available for the X6DA8-G/X6DA8-G2 only.
- 2. There are two Gigabit LAN ports on the X6DA8-G2/X6DAE-G2 and only one Gigabit LAN on the X6DA8-G and the X6DAE-G.

Figure 1-2. SUPER● X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2 Motherboard Layout

(not drawn to scale)



- 1. Jumpers not indicated are for test purposes only.
- 2. See Chapter 2 for detailed information on jumpers, I/O ports and JF1 front panel connections.
- 3. "■" indicates the location of Pin 1.
- 4. SCSI is available for the X6DA8-G/X6DA8-G2 only.
- 5. There are two Gigabit LAN ports on the X6DA8-G2/X6DAE-G2 and only one Gigabit LAN on the X6DA8-G and the X6DAE-G.
- 6. The graphics shown in this manual were based upon the latest PCB Revision available at the time of publishing of this manual. The motherboard you've received may or may not look exactly the same as the graphics shown in this manual.

Quick Reference

<u>Jumper</u>	<u>Description</u>	Default Setting
JP13	3rd PWR Supply Failure Enable	Open (Disabled)
JPA1	SCSI Controller Enabled(X6DA8-G/0	G2)Pins 1-2 (Enabled)
JPA2/JPA3	SCSI Ch. A/B Term.Ena.(X6DA8-G/0	G2)Open(Enabled)
JPC1	Audio Enable/Disable	Pins 1-2 (Enabled)
JPF	Force Power	Open (Disabled)
JPL1	Giga-bit LAN Enable/Disable	Pins 1-2 (Enabled)
JWD	Watch Dog Enable	Pins 1-2 (Reset)
XJ4F1/XJ4F2	PLL Select (*X6DA8-G/X6DAE-G)	Closed (333MHz)

Connector	<u>Description</u>
ATX PWR (J1B4)	Primary 24-pin ATX PWR Connector
12V PWR (J1D1, J32)	12V 8-pin PWR/12V 4-pin CPU PWR Connectors
COM1 (J6)/COM2 (J39)	COM1/COM2 Serial Port Connectors
FAN #1-#8	CPU Fan1/CPU Fan2/Chassis Fans Headers
DIMM#1A-#4B	Memory (RAM) Slots#(1A,1B, 2A,2B, 3A,3B,4A,4B)
GLAN1	G-bit Ethernet Ports
GLAN2	G-bit Ethernet Ports (*X6DA8-G2/DAE-G2 only)
IDE1(J3), IDE2(J4)	IDE1/2 Hard Disk Drive Connectors
J9	Keyboard/Mouse
J20	IPMI 2.0 Connector
J22	System Management Bus Connector
J23	Parallel (Printer) Port
J24	PWR System Management Bus
JA1, JA2	Ultra 320 SCSI Channel A,Channel B(X6DA8-G/G2)
JBT1	CMOS Clear (JBT1 is a pad:See Chapter 2)
JD1	PWR LED (Pins1-3), Speaker (Pins 4-7)
JF1	Front Panel Control
JK1	Keylock
JL1	Chassis Intrusion Header
JOH1	Overheat LED
JP8	Floppy Disk Drive Connector
JP12	Power Fault Connector
JP14	PWR Fail Alarm Reset
PCIX#1,#2,#3(J12-J14)	PCIX-100MHz ZCR,PCIX-100MHz/PCIX-133MHzslots
PCI#5(J19)	PCI-33 MHz slot
PCI-Express#4,#6	x4/x16 PCI-Express slots
SATA0/1	Serial ATA0/Serial ATA1 Headers
JWOL	Wake-on-LAN Header
JWOR1	Wake-on-Ring Header
USB#0-3(J40)	(Back Panel) Universal Serial Bus Ports
USB#4-5,6-7(JD3, JD2)	(Front Panel) Universal Serial Bus Headers

Motherboard Features

CPU

Single or dual Intel[®] 604-pin 64-bit/32-bit Nocona[™] processors at 800 MHz front side (system) bus speed. (*Notes: CPU FSB speed is set by Manufacturer. Please refer to the support section of our web site for a complete listing of supported processors (http://www.supermicro.com/TechSupport.htm.)

Memory

- Eight 240-pin DIMM sockets supporting up to 16 GB Registered ECC DDR2-400 (PC3200) SDRAM (*X6DA8-G2/X6DAE-G2 only)
- Eight 184-pin DIMM sockets supporting up to 32 GB Registered ECC DDR-333/266 (PC2700/PC2100)SDRAM(-16 GB for PC2700, 32GB for PC2100) (*X6DA8-G/X6DAE-G only)

Notes: 1. Memory size is set via BIOS. 2. Interleaved memory; requires memory modules to be installed in pairs. See Section 2-3 for details.

Chipset

• Intel E7525 (Tumwater) chipset

Expansion Slots

- One PCI-e slot (*x16@4GB/sec)
- One PCI-e slot (*x4@2GB/sec)
- Three 64-bit PCI-X slots (*One 64-bit PCI-X-133 slot, one PCI-X-100 slot, One PCI-X-100MHz ZCR)
- One 32-bit 33MHz PCI slot (w/PCI Graphic Card support)

BIOS

- 8 Mb Phoenix BIOS ROM
- APM 1.2, DMI 2.1, PCI 2.2, ACPI 1.0, Plug and Play (PnP), SMBIOS 2.3

PC Health Monitoring

- Onboard voltage monitors for CPU cores, chipset voltage, 3.3V, +5V, +12V, -12V and 3.3V standby
- · Fan status monitor by Thermal Management via BIOS
- · CPU/chassis temperature monitors
- Environmental temperature monitor via Supero Doctor III
- · CPU fan auto-off in sleep mode
- · CPU slow-down on temperature overheat
- CPU thermal trip support for processor protection, +5V standby alert

LFD

- · Power-up mode control for recovery from AC power loss
- · System overheat LED and control
- · Chassis intrusion detection
- System resource alert via Super Doctor III.

ACPI Features

- · Microsoft OnNow
- · Slow blinking LED for suspend state indicator
- · Main switch override mechanism

Onboard I/O

- Adaptec 7902 dual channel Ultra 320 SCSI (*X6DA8-G/X6DA8-G2 only)
- One IPMI 2.0
- One Intel 8254x Gigabit Ethernet controller(*X6DA8/X6DAE-G:1 LAN, X6DA8/X6DAE-G2:2 LAN ports)
- 2 EIDE Ultra DMA/100 bus master interfaces
- 1 floppy port interface (up to 2.88 MB)
- 1 EPP/ECP Parallel Port
- PS/2 mouse and PS/2 keyboard ports
- Up to eight USB 2.0 (Universal Serial Bus):
- (4 Back Panel USB ports & 4 Front Panel USB headers)
- · 2 serial ports
- 2 Serial ATA support (w/RAID 0/RAID 1 support)

Other

- · Internal/external modem ring-on
- Wake-on-Ring (WOR)
- Wake-on-LAN (WOL)
- · Console redirection

CD/Diskette Utilities

· BIOS flash upgrade utility and device drivers

Dimensions

• ATX Ext. 12" x 13.05" (304.8 x 331.5 mm)

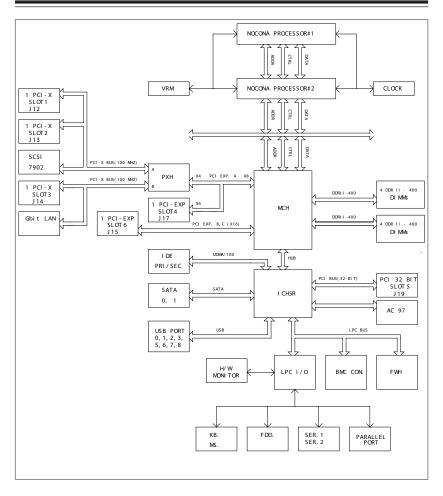


Figure 1-9. Block Diagram of the E7525 Tumwater Chipset

Note: This is a general block diagram. Please see the previous Motherboard Features pages for details on the features of each motherboard.

1-2 Chipset Overview

Built upon the functionality and the capability of the E7525 Tumwater chipset, the X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2 motherboard provides the performance and feature set required for dual processor-based computer systems, with configuration options optimized for communications, presentation, storage, computation or database applications. The Intel E7525 Tumwater chipset consists of the following components: the E7525 Tumwater Memory Controller Hub (MCH), the I/O Controller Hub (ICH5R), and the PCI-X Hub (PXH).

The E7525 Tumwater MCH supports single or dual Nocona processors with Front Side Bus speeds of up to 800 MHz(*Note). Its memory controller provides direct connection to two channels of registered DDR333 or DDR2 400 with a marched system bus address and data bandwidths of up to 2.67 GB/s (DDR 333) or 3.2 GB/s (DDR2-400) per channel. The E7525 Tumwater also supports the new PCI Express high speed serial I/O interface for superior I/O bandwidth. The MCH provides configurable x16 PCI Express interfaces which may alternatively be configured as two independent x8 PCI Express interfaces. These interfaces support connection of the MCH to a variety of other bridges that are compliant with the PCI Express Interface Specification, Rev. 1.0a, such as 82546GB GLAN Adaptor, the Dobson I/O processor, H/W RAID controllers and TCP/IP Off-load engines. The MCH interfaces with the ICH5R ICH I/O Controller Hub via HI 1.5 Hub Interface. The PXH can be configured to support for 32- or 64-bit PCI devices running at 33 MHz, 66 MHz, 100 MHz, and 133 MHz.

ICH5R System Features

In addition to providing the I/O subsystem with access to the rest of the system, the ICH5R I/O Controller Hub integrates many I/O functions.

The ICH5 I/O Controller Hub integrates: 2-channel Ultra ATA/100 Bus Master IDE Controller, two Serial ATA (SATA) Host w/RAID0, RAID1 support, SMBus 2.0 Controller, LPC/Flash BIOS Interface, PCI 2.2 Interface and System Management Controller.

(*Notes: The CPU FSB speed is set at 800 MHz by the Manufacturer.)

1-3 Special Features

Recovery from AC Power Loss

BIOS provides a setting for you to determine how the system will respond when AC power is lost and then restored to the system. You can choose for the system to remain powered off (in which case you must hit the power switch to turn it back on) or for it to automatically return to a power-on state. See the Power Lost Control setting in the Advanced BIOS Setup section (Boot Features) to change this setting. The default setting is Always On.

1-4 PC Health Monitoring

This section describes the PC health monitoring features of the SUPER X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2. All have an onboard System Hardware Monitor chip that supports PC health monitoring.

Onboard Voltage Monitors for the CPU Cores, Chipset Voltage, +3.3V, +5V, +12V, -12V and +3.3V Standby

An onboard voltage monitor will scan these voltages continuously. Once a voltage becomes unstable, a warning is given or an error message is sent to the screen. Users can adjust the voltage thresholds to define the sensitivity of the voltage monitor.

Fan Status Monitor with Firmware/Software On/Off Control

The PC health monitor can check the RPM status of the cooling fans. The onboard 4-pin CPU and chassis fans are controlled by the power management functions. The thermal fan is controlled by the overheat detection logic.

Environmental Temperature Control via Supero DoctorIII

The thermal control sensor monitors the CPU temperature in real time and will turn on the thermal control fan whenever the CPU temperature exceeds a user-defined threshold. The overheat circuitry runs independently from the CPU. It can continue to monitor for overheat conditions even when the CPU is in sleep mode. Once it detects that the CPU temperature is too high, it will automatically turn on the thermal control fan to prevent any overheat

damage to the CPU. The onboard chassis thermal circuitry can monitor the overall system temperature and alert users when the chassis temperature is too high.

CPU Fan Auto-Off in Sleep Mode

The CPU fan activates when the power is turned on. It continues to operate when the system enters Standby mode. When in sleep mode, the CPU will not run at full power, thereby generating less heat.

CPU Overheat LED and Control

This feature is available when the user enables the CPU overheat warning function in the BIOS. This allows the user to define an overheat temperature. When this temperature is exceeded, both the overheat fan and the warning LED are triggered.

System Resource Alert (via Supero DoctorIII)

This feature is available when used with Intel's LANDesk Client Manager (optional). LDCM is used to notify the user of certain system events. For example, if the system is running low on virtual memory and there is insufficient hard drive space for saving the data, you can be alerted of the potential problem.

Auto-Switching Voltage Regulator for the CPU Core

The auto-switching voltage regulator can auto-detect and regulate power supply to the CPU. This will allow the regulator to run cooler and thus make the system more stable.

1-5 ACPI Features

ACPI stands for Advanced Configuration and Power Interface. The ACPI specification defines a flexible and abstract hardware interface that provides a standard way to integrate power management features throughout a PC system, including its hardware, operating system and application software. This enables the system to automatically turn on and off peripherals such as CD-ROMs, network cards, hard disk drives and printers. This also includes consumer devices connected to the PC such as VCRs, TVs, telephones and stereos.

In addition to enabling operating system-directed power management, ACPI provides a generic system event mechanism for Plug and Play and an operating system-independent interface for configuration control. ACPI leverages the Plug and Play BIOS data structures while providing a processor architecture-independent implementation that is compatible with Windows 2000. Windows XP, Windows NT 5.0 and Windows 2003.

Microsoft OnNow

The OnNow design initiative is a comprehensive, system-wide approach to system and device power control. OnNow is a term for a PC that is always on but appears to be off and responds immediately to user or other requests.

Slow Blinking LED for Suspend-State Indicator

When the CPU goes into a suspend state, the chassis power LED will start blinking to indicate that the CPU is in suspend mode. When the user presses any key, the CPU will wake-up and the LED will automatically stop blinking and remain on.

Main Switch Override Mechanism

When an ATX power supply is used, the power button can function as a system suspend button to make the system enter a SoftOff state. The monitor will be suspended and the hard drive will spin down. Depressing the power button again will cause the whole system to wake-up. During the SoftOff state, the ATX power supply provides power to keep the required circuitry in the system alive. In case the system malfunctions and you want to turn off the power, just depress and hold the power button for 4 seconds. This option can be set in the Power section of the BIOS Setup routine.

External Modem Ring-On (WOR)

Wake-up events can be triggered by a device such as the external modem ringing when the system is in the SoftOff state. Note that external modem ring-on can only be used with an ATX 2.01 (or above) compliant power supply.

1-6 Power Supply

As with all computer products, a stable power source is necessary for proper and reliable operation. It is even more important for processors that have high CPU clock rates.

The SUPER X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2 accommodates ATX power supplies. Although most power supplies generally meet the specifications required by the CPU, some are inadequate. You should use one that will supply at least 400W of power (*Note: the 12V 8-pin power connector (J1D1) is required for CPU power consumption, and an additional 12V 4-pin power connection (J32) is also required to ensure adequate power supply to the system.) Also your power supply must supply 1.5A for the Ethernet ports. It is strongly recommended that you use a high quality power supply that meets ATX power supply Specification 2.02 or above. It must also be SSI compliant (info at http://www.ssiforum.org/). Additionally, in areas where noisy power transmission is present, you may choose to install a line filter to shield the computer from noise. It is recommended that you also install a power surge protector to help avoid problems caused by power surges.

1-7 Super I/O

The disk drive adapter functions of the Super I/O chip include a floppy disk drive controller that is compatible with industry standard 82077/765, a data separator, write pre-compensation circuitry, decode logic, data rate selection, a clock generator, drive interface control logic and interrupt and DMA logic. The wide range of functions integrated onto the Super I/O greatly reduces the number of components required for interfacing with floppy disk drives. The Super I/O supports 360 K, 720 K, 1.2 M, 1.44 M or 2.88 M disk drives and data transfer rates of 250 Kb/s, 500 Kb/s or 1 Mb/s.It also provides two high-speed, 16550 compatible serial communication ports (UARTs), one of which supports serial infrared communication. Each UART includes a 16-byte send/receive FIFO, a programmable baud rate generator, complete modem control capability and a processor interrupt system. Both UARTs provide legacy speed with baud rate of up to 115.2 Kbps as well as an advanced speed with baud rates of 250 K, 500 K, or 1 Mb/s, which support higher speed modems.

The Super I/O supports one PC-compatible printer port (SPP), Bi-directional Printer Port (BPP), Enhanced Parallel Port (EPP) or Extended Capabilities Port (ECP).

The Super I/O provides functions that comply with ACPI (Advanced Configuration and Power Interface), which includes support of legacy and ACPI power management through an SMI or SCI function pin. It also features auto power management to reduce power consumption.

The IRQs, DMAs and I/O space resources of the Super I/O can flexibly adjust to meet ISA PnP requirements, which support ACPI and APM (Advanced Power Management).

Chapter 2 Installation

2-1 Static-Sensitive Devices

Electric-Static-Discharge (ESD) can damage electronic components. To prevent damage to your system board, it is important to handle it very carefully. The following measures are generally sufficient to protect your equipment from ESD.

Precautions

- · Use a grounded wrist strap designed to prevent static discharge.
- Touch a grounded metal object before removing the board from the antistatic bag.
- Handle the board by its edges only; do not touch its components, peripheral chips, memory modules or gold contacts.
- · When handling chips or modules, avoid touching their pins.
- Put the motherboard and peripherals back into their antistatic bags when not in use.
- For grounding purposes, make sure your computer chassis provides excellent conductivity between the power supply, the case, the mounting fasteners and the motherboard.
- Use only the correct type of onboard CMOS battery as specified by the manufacturer. Do not install the onboard battery upside down to avoid possible explosion.

Unpacking

The motherboard is shipped in antistatic packaging to avoid static damage. When unpacking the board, make sure the person handling it is static protected.

2-2 Nocona Processor and Heatsink Installation

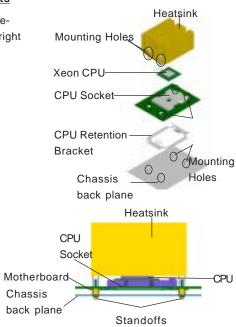


When handling the processor package, avoid placing direct pressure on the label area of the fan. Also, do not place the motherboard on a conductive surface, which can damage the BIOS battery and prevent the system from booting up.

IMPORTANT: Always connect the power cord last and always remove it before adding, removing or changing any hardware components. Make sure that you install the processor into the CPU socket **before** you install the CPU heat sink.

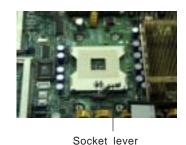
Installing Retention Brackets

(*CPU Retention Plates are preinstalled. Pictures shown on right are for reference only.)



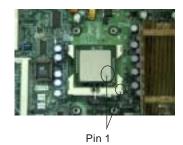
CPU Installation

1. Lift the lever on the CPU socket: lift the lever completely as shown on the picture on the right; otherwise, you will damage the CPU socket when power is applied. (Install CPU1 first.)



2-2

- 2. Insert the CPU in the socket, making sure that pin 1 of the CPU aligns with pin 1 of the socket (both corners are marked with a triangle). When using only one CPU, install it into CPU socket #1 (socket #2 is automatically disabled if only one CPU is used).
- Press the lever down until you hear the *click* so you can be sure that the CPU is securely installed in the CPU socket.

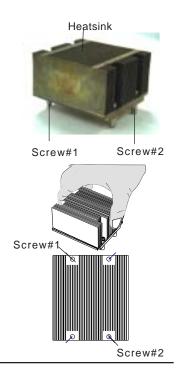




Socket lever in the locking Position

Heatsink Installation

- Do not apply any thermal compound to the heatsink or the CPU die-the required amount has already been applied.
- Place the heatsink on top of the CPU so that the four mounting holes are aligned with those on the retention mechanism.
- 3. Screw in two diagonal screws (ie the #1 and the #2 screws) until just snug (-do not fully tighten the screws to avoid possible damage to the CPU.)
- 4. Finish the installation by fully tightening all four screws.



To Un-install the Heatsink

(Caution! We do not recommend that the CPU or the heatsink be removed. However, if you do need to un-install the heatsink, please follow the instructions below to uninstall the heatsink to prevent damage done to the CPU or the CPU socket.)

- 1. Unscrew and remove the heatsink screws from the motherboard in the sequence as show in the picture on the right.
- 2. Hold the heatsink as show in the picture on the right and gently wriggle the heatsink to loosen it from the CPU. (Do not use excessive force when wriggling the heatsink!!)
- 3. Once the CPU is loosened from the heatsink, remove the heatsink from the CPU socket.
- 4. Clean the surface of the CPU and the heatsink to get rid of the old thermal grease. Reapply the proper amount of thermal grease on the surface before you re-install the CPU and the heatsink.

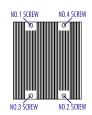
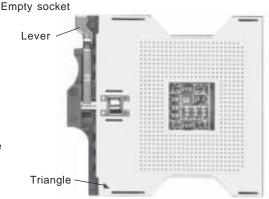


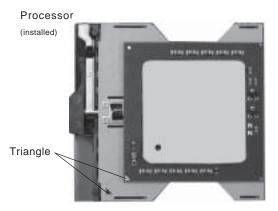


Figure 2-1. PGA604 Socket: Empty and with Processor Installed



Warning! Make sure you lift the lever completely when installing the CPU. If the lever is only partly raised, damage to the socket or CPU may result.





Mounting the Motherboard in the Chassis

All motherboards have standard mounting holes to fit different types of chassis. Make sure that the locations of all the mounting holes for both the motherboard and the chassis match. Although a chassis may have both plastic and metal mounting fasteners, metal ones are highly recommended because they ground the motherboard to the chassis. Make sure that the metal standoffs click in or are screwed in tightly. Then, use a screwdriver to secure the motherboard onto the motherboard tray. (*Note: some components are very close to the mounting holes. Please take precautionary measures to prevent damage done to these components when you install the motherboard to the chassis.)

2-3 Installing DIMMs

Note: Check the Supermicro web site for recommended memory modules.

CAUTION

Exercise extreme care when installing or removing DIMM modules to prevent any possible damage. Also note that the memory is interleaved to improve performance (see step 1).

DIMM Installation (See Figure 2-2)

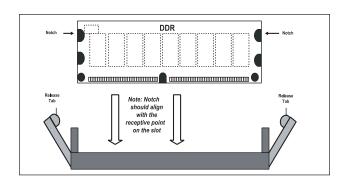
- Insert the desired number of DIMMs into the memory slots, starting with DIMM #1A. The memory scheme is interleaved so <u>you must install two</u> modules at a time, beginning with DIMM #1A, then DIMM #1B, and so on.
- Insert each DIMM module vertically into its slot. Pay attention to the notch along the bottom of the module to prevent inserting the DIMM module incorrectly.
- 3. Gently press down on the DIMM module until it snaps into place in the slot. Repeat for all modules (see step 1 above).

Memory Support

The X6DA8-G2/X6DAE-G2 supports up to 16 GB of Reg. ECC DDR2 400 (PC3200) memory. The X6DA8-G/X6DAE-G supports up to 32 GB of Registered ECC DDR 333/266 (PC2700/PC2100) memory. (*The motherboard supports up to 32GB for PC2100, 16 GB for PC 2700.) All motherboards were designed to support 4 GB modules in each slot, but has only been verified for up to 2 GB modules. (*For DDR333: Maximum of 4 double-banked memory modules, or maximum of 6 single-banked memory modules are supported.)

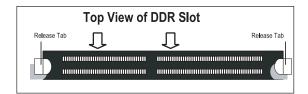
Figure 2-2. Installing and Removing DIMMs

To Install:
Insert module vertically and press down until it snaps into place.
Pay attention to the alignment notch at the bottom.



To Remove:

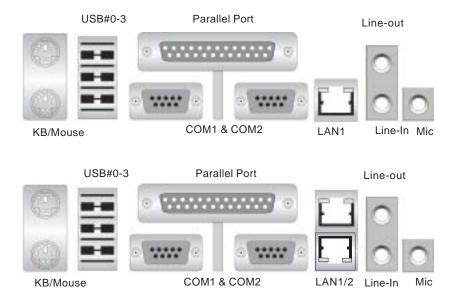
Use your thumbs to gently push near the edge of both ends of the module. This should release it from the slot.



2-4 I/OPorts/Control Panel Connectors

The I/O ports are color coded in conformance with the PC 99 specification. See Figure 2-3 below for the colors and locations of the various I/O ports.

*X6DA8-G/X6DAE-G



*X6DA8-G2/X6DAE-G2

Figure 2-3. I/O Port Locations and Definitions

Front Control Panel

JF1 contains header pins for various buttons and indicators that are normally located on a control panel at the front of the chassis. These connectors are designed specifically for use with Supermicro server chassis. See Figure 2-4 for the descriptions of the various control panel buttons and LED indicators. Refer to the following section for descriptions and pin definitions.

19 Ground 0 0 NMI Χ Х 0 0 Power LED Vcc 0 0 HDD LED 0 0 Vcc NIC1 LED 0 Vcc (*NIC2 LED) 0 0 Vcc Overheat LED 0 0 Vcc Power Fail LED 0 0 Vcc 0 Reset > Reset Button 0 Ground Power Button Pwr Ground

Figure 2-4. JF1 Header Pins

(*Note: NIC2 is for X6DA8-G2/X6DAE-G2 only.)

2-5 Connecting Cables

ATX Power Connector

There are a 24-pin main power supply connector(PW1:J1B4) and a 4-pin CPU PWR connector (J32) on the board. These power connectors meet the SSI EPS 12V specification. You can also use a 20-pin PWR supply; however, the 4-pin 12V PWR supply is required to ensure sufficient power supply. See the table on the right for pin definitions. For CPU PWR (J1D1), please refer to the item listed below.

ATX Power Supply 24-pin Connector Pin Definitions (J1B4)

Pin Numbe	er Definition	Pin Num	ber Definition
13	+3.3V	1	+3.3V
14	-12V	2	+3.3V
15	COM	3	COM
16	PS_ON#	4	+5V
17	COM	5	COM
18	COM	6	+5V
19	COM	7	COM
20	Res(NC)	8	PWR_OK
21	+5V	9	5VSB
22	+5V	10	+12V
23	+5V	11	+12V
24	COM	12	+3.3V

+12V 4-pin Connector (J32)

Required Connection

Pins #	Definition	
1 & 2	Ground	
3 & 4	+12 V	

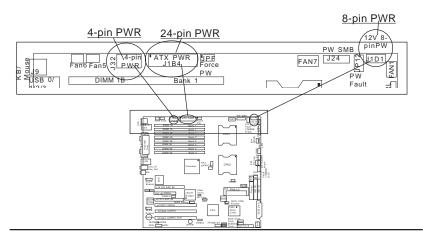
Processor Power Connector

In addition to the Primary ATX power connector (above), the 12v 8-pin Processor connector at J1D1 must also be connected to your power supply. See the table on the right for pin definitions.

CPU 8-Pin PWR Connector (J1D1)

Required
Connection

Pins Definition
1 thru 4 Ground
5 thru 8 +12v



NMI Button

The non-maskable interrupt button header is located on pins 19 and 20 of JF1. Refer to the table on the right for pin definitions.

NMI Button Pin Definitions (JF1)

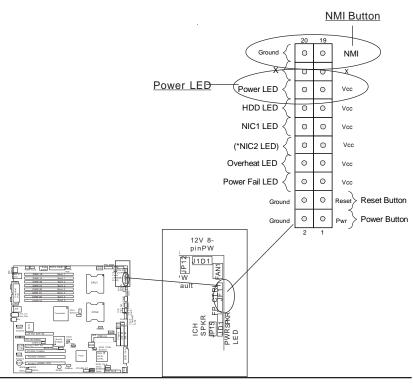
Pin	
Number	Definition
19	Control
20	Ground

Power LED

The Power LED connection is located on pins 15 and 16 of JF1. Refer to the table on the right for pin definitions.

PWR_LED Pin Definitions

(01.1)		
Pin		
Number	Definition	
15	Vcc	
16	Control	



HDD LED

The HDD LED connection is located on pins 13 and 14 of JF1. Attach the hard drive LED cable here to display disk activity (for any hard drives on the system, including SCSI, Serial ATA and IDE). See the table on the right for pin definitions.

HDD LED Pin Definitions

(JF1)		
Pin		
Number	Definition	
13	Vcc	
14	HD Active	

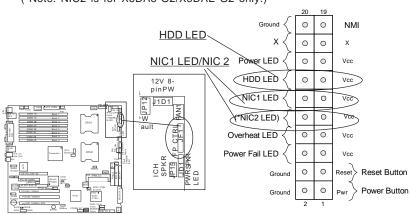
NIC1 LED/NIC 2 LED Indicators

The NIC1 (Network Interface Controller) LED connections for the GLAN port1 is located on pins 11 and 12 of JF1 and the NIC2 LED connectors are located on Pins 9 and 10 of JF. (*NIC 2 is available for the X6DA8-G2/X6DAE-G2 only.) Refer to the tables on the right for pin definitions.

NIC1 LED Pin Definitions

(01.1)		
Pin		
Number	Definition	
11	Vcc	
12	GND	

(*Note: NIC2 is for X6DA8-G2/X6DAE-G2 only.)



Overheat/Fan Fail LED

Connect an LED to the OH/Fan Fail connection on pins 7 and 8 of JF1 to provide advanced warning of chassis overheating. This LED will blink to indicate a fan failure. Refer to the table on the right for pin definitions.

Overheat (OH)/Fan Fail LED Pin Definitions (JF1)

Pin	
Number	Definition
7	Vcc
8	GND

Overheat/Fan Fail LED

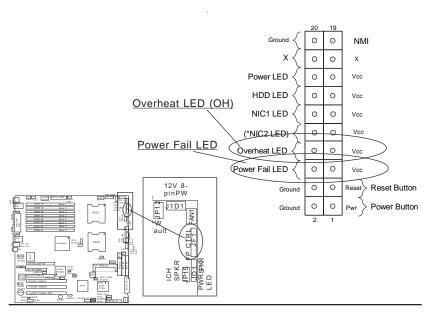
Message
Overheat
Fan Fail

Power Fail LED

The Power Fail LED connection is located on pins 5 and 6 of JF1. Refer to the table on the right for pin definitions.

Power Fail LED Pin Definitions (JF1)

(JF1)		
Pin		
Number	Definition	
5	Vcc	
6	GND	



Reset Button

The Reset Button connection is located on pins 3 and 4 of JF1. Attach it to the hardware reset switch on the computer case. Refer to the table on the right for pin definitions.

Reset Pin Definitions (JF1)

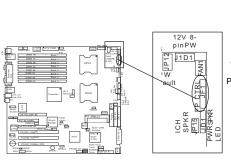
()		
Pin		
Number	Definition	
3	Reset	
4	Ground	

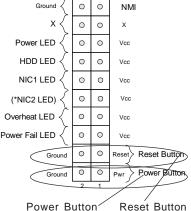
Power Button

The Power Button connection is located on pins 1 and 2 of JF1. Momentarily contacting both pins will power on/off the system. This button can also be configured to function as a suspend button (with a setting in BIOS - see Chapter 4). To turn off the power when set to suspend mode, depress the button for at least 4 seconds. Refer to the table on the right for pin definitions.

Power Button Connector Pin Definitions

(0)		
Pin		
Number	Definition	
1	PW_ON	
2	Ground	





Chassis Intrusion

A Chassis Intrusion header is located at JL1. Attach the appropriate cable from chassis to inform you of a chassis intrusion.

Chassis Intrusion		
Pin Definitions (JL1)		
Pin		
Number	Definition	
1	Intrusion Input	
2	Ground	

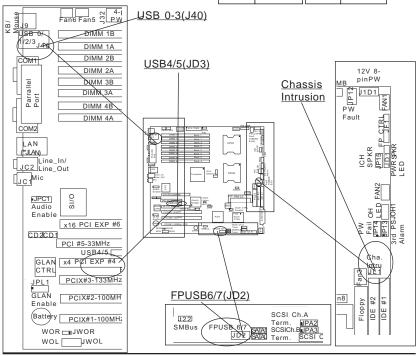
Universal Serial Bus (USB)

There are eight USB 2.0 (Universal Serial Bus) ports/headers on the motherboard. Four of them are Back Panel USB ports (USB#0-3:J40), and the other four are Front Panel USB headers (USB#4,5-JD3, USB#6,7-JD2). See the tables on the right for pin definitions.

USB Pin Definition J40 (Back Panel USB) Pin# Definition 1 +5V 2 P03 P0+ 4 Ground

JD2 & JD3 (FP USB)

Pin		Pin	
Number	Definition	Number	Definition
1	+5V	2	+5V
3	PO-	4	PO-
5	PO+	6	PO+
7	Ground	8	Ground
		10	Ground



ATX PS/2 Keyboard and PS/2 Mouse Ports

The ATX PS/2 keyboard and the PS/2 mouse are located at J9. See the table on the right for pin definitions. (The mouse port is above the keyboard port. See the table on the right for pin definitions.)

PS/2 Keyboard and Mouse Port Pin Definitions (J9)

Pin	
Number	Definition
1	Data
2	NC
3	Ground
4	VCC
5	Clock
6	NC

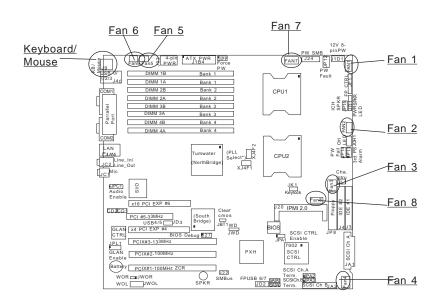
Fan Headers

There are eight fan headers (Fan 1 to Fan 8) on the X6DA8-G/X6DAE-G/X6DAE-G2. See the table on the right for pin definitions. (*Note: These fan headers are 4-pin fans. Pins 1-3 of the fan headers are backward compatible with the traditional 3-pin fans.)

4-pin Fan Header Pin Definitions (CPU and Chassis Fans)

Pin#	Definition
1	Ground (black)
2	+12V (red)
3 4	Tachometer PWR_Control

Caution: These fan headers use DC power.



Wake-On-Ring

The Wake-On-Ring header is designated JWOR1. This function allows your computer to receive and "wake-up" by an incoming call to the modem when in suspend state. See the table on the right for pin definitions. You must have a Wake-On-Ring card and cable to use this feature.

Wake-on-Ring Pin Definitions (JWOR1)

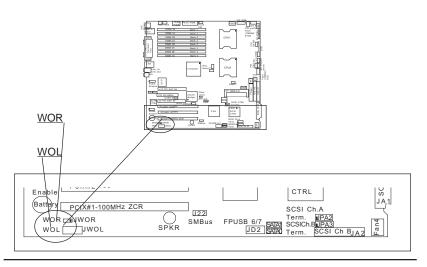
Pin Number	Definition
1 2	Ground Wake-up

Wake-On-LAN

The Wake-On-LAN header is located at JWOL on the mother-board. See the table on the right for pin definitions. (You must also have a LAN card with a Wake-On-LAN connector and cable to use this feature.)

Wake-On-LAN Pin Definitions (JWOL)

Pin	
Number	Definition
1	+5V Standby
2	Ground
3	Wake-up



GLAN (Giga-bit Ethernet Port)

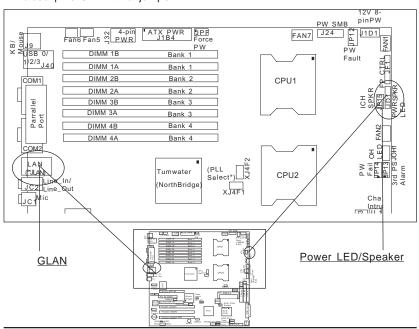
A G-bit Ethernet port is located beside the COM2 port on the IO backplane. This port accepts RJF1 type cables. (*two GLAN ports for the X6DA8-G2/X6DAE-G2, one GLAN port for the X6DA8-G/X6DAE-G.)

Power LED/Speaker

On the JD1 header, pins 1-3 are for a power LED and pins 4-7 are for the speaker. See the table on the right for speaker pin definitions. Note: The speaker connector pins are for use with an external speaker. If you wish to use the onboard speaker, you should close pins 6-7 with a jumper.

Speaker Connector Pin Definitions (JD1)

Pin		
Number	Function	Definition
4	+	Red wire, Speaker data
5	Key	No connection
6		Key
7		Speaker data



Power Fault

Connect a cable from your power supply to the Power Fail header (JP12) to provide warning of power supply failure. This warning signal is passed through the PWR_LED pin to indicate of a power failure on the chassis. See the table on the right for pin definitions.

Power Fail Pin Definitions (JP12)

Г	Pin	
I	lumber	Definition
Г	1	P/S 1 Fail Signal
	2	P/S 2 Fail Signal
	3	P/S 3 Fail Signal
	4	Reset (from MB)

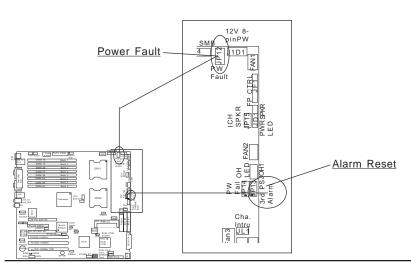
Note: This feature is only available when using redundant Supermicro power supplies.

Alarm Reset

If three power supplies are installed and JP14 is enabled, the system will notify you when any of the three power modules fails. Connect JP13 to a micro-switch to enable you to turn off the alarm that sounds when a power module fails. See the table on the right for pin definitions.

Alarm Reset Jumper Settings (JP13)

Jumper Position	Definition
Pin 1	Ground
Pin 2	+5V



SMB

A System Management Bus header is located at J22. Connect the appropriate cable here to utilize SMB on your system.

Overheat LED/Fan Fail (JOH1)

The JOH1 header is used to connect an LED to provide warning of chassis overheating. This LED will blink to indicate a fan failure. Refer to the table on right for pin definitions.

SMB Header Pin Definitions (J22)

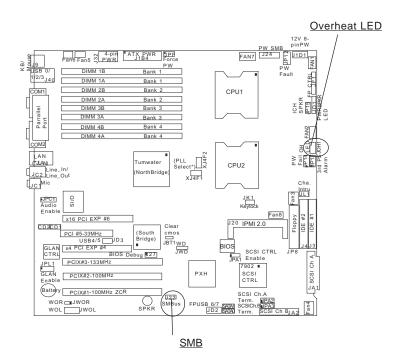
Definition
Data
Ground
Clock
No Connection

Table 2-15 Overheat LED Pin Definitions (JOH1)

Pin Number	Definition
1	OH Active
2	Ground

Overheat/Fan Fail LED

State	
	Message
Solid Blink	Overheat Fan Fail



SMB Power (I²C) Connector

I² C Connector (J24), located between the PWR ForceOn Header and the PWR Fault header, monitors the status of PWR Supply, Fan and system temperature.

SMB PWR Pin Definitions (J24)

Pin#	Definition
1	Clock
2	Data
3	N/A
4	N/A
5	N/A
	1 2 3 4

AC'97 Output & Audio Enable

AC'97 provides high quality onboard audio. The X6DA8-G/X6DAE-G/X6DAE-G/X6DA8-G2/X6DAE-G2 features 6-channel sound for front L&R, rear L&R, center and subwoofer speakers. This feature is activated with the Advanced software (on the CD-ROM included with your motherboard). Sound is then output through the Line In, Line Out and MIC jacks (see at right). To activate the Onboard Audio, please enable the Jumper: JPC1. See the table on right for pin definitions.



Blue: Line In(surround

sound L/R)

Green: Line Out(Front L/R)

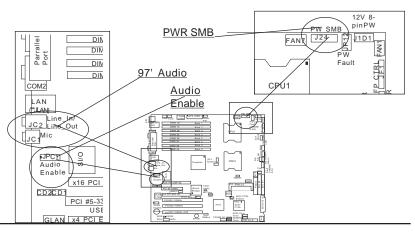


Pink: MIC In (Center/

subwoofer)

AC97 Enable/Disable Jumper Settings (JPC1)

Jumper		
Position	Definition	
1-2	Enabled	
2-3	Disabled	



Keylock

The keyboard lock connection is located on JK1. Utilizing this header allows you to inhibit any actions made on the keyboard, effectively "locking" it.

Keylock (JK1)

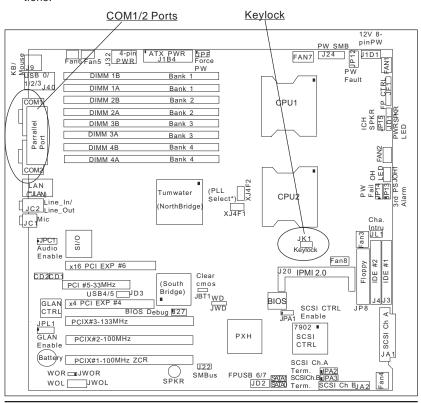
Jumper	
Position	Definition
1	Ground
2	Keylock R-N

Serial Ports

The COM1 (J3) and COM2 (J4) serial ports are located under the parallel port (see Figure 2-3). See the table on the right for pin definitions.

Serial Port Pin Definitions (COM1, COM2)

(,				
Pin Number	Definition	Pin Number	Definition	
1	CD	6	DSR	
2	RD	7	RTS	
3	TD	8	CTS	
4	DTR	9	RI	
5	Ground	10	NC	

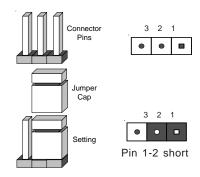


2-6 Jumper Settings

Explanation of Jumpers

To modify the operation of the motherboard, jumpers can be used to choose between optional settings. Jumpers create shorts between two pins to change the function of the connector. Pin 1 is identified with a square solder pad on the printed circuit board. See the motherboard layout pages for jumper locations.

Note: On two pin jumpers, "Closed" means the jumper is on and "Open" means the jumper is off the pins.

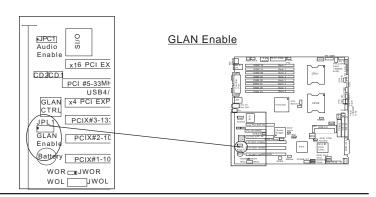


GLAN Enable/Disable

JPL1 enables or disable the GLAN port on the motherboard. See the table on the right for jumper settings. The default setting is enabled.

GLAN Enable/Disable Jumper Settings (JPL1)

		. ,
	Jumper	
ı	Position	Definition
	Pins 1-2	
	Pins 2-3	Disabled

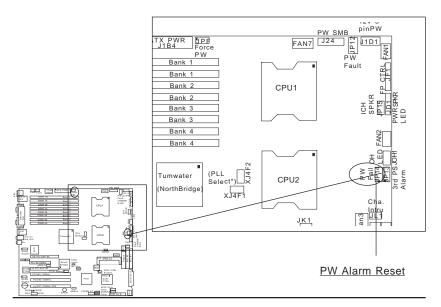


Power Supply Alarm Enable/Disable

The system can notify you in the event of a power supply failure. This feature assumes that three power supply units are installed in the chassis, with one acting as a backup. If you only have one or two power supply units installed, you should disable this (the default setting) with JP14 to prevent false alarms. See the table on right for pin definitions.

Power Supply Alarm Enable/Disable Jumper Settings (JP14)

dumper detaings (or 14)		
Jumper		
Position	Definition	
Open	Disabled	
Closed	Enabled	



CMOS Clear

JBT1 is used to clear CMOS. Instead of pins, this "jumper" consists of contact pads to prevent the accidental clearing of CMOS. To clear CMOS, use a metal object such as a small screwdriver to touch both pads at the same time to short the connection. Always remove the AC power cord from the system before clearing CMOS. **Note:** For an ATX power supply, you must completely shut down the system, remove the AC power cord and then short JBT1 to clear CMOS.

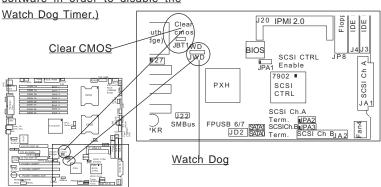


Watch Dog Enable/Disable

JWD enables the Watch Dog function. Watch Dog is a system monitor that can reboot the system when a software application is "hung up". Pins 1-2 will cause WD to reset the system if an application is "hung up". Pins 2-3 will generate a non-maskable interrupt signal for the application that is "hung up". See the table on the right for jumper settings. Watch Dog can also be enabled via BIOS. (*Note, when enabled, the user needs to write his own application software in order to disable the

Watch Dog Jumper Settings (JWD)

Jumper	
Position	Definition
Pins 1-2	
Pins 2-3	WD to NMI
Open	Disabled



SCSI Controller Enable/ Disable (*ForX6DA8-G/ X6DA8-G2 only)

Jumper JPA1 allows you to enable or disable the SCSI headers. The default setting is pins 1-2 to enable all four headers. See the table on the right for jumper settings.

SCSI Termination Enable/ Disable (*ForX6DA8-G/ X6DA8-G2 only)

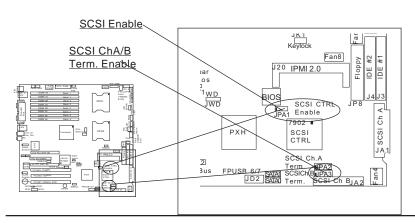
Jumpers JPA2 and JPA3 allow you to enable or disable termination for the SCSI connectors. Jumper JPA2 controls SCSI channel A and JPA3 is for SCSI channel B. The default setting is open to enable (terminate) both SCSI channels. (*Note: In order for the SCSI drives to function properly, please do not change the default setting set by the manufacturer.) See the table on the right for jumper settings.

SCSI Enable/Disable Jumper Settings (JPA1)

Jumper Position	Definition
Pins 1-2 Pins 2-3	

SCSI Channel Termination Enable/Disable Jumper Settings

(JFAZ, JFAS)			
Jumper			
Position	Definition		
Open	Enabled		
Closed	Disabled		



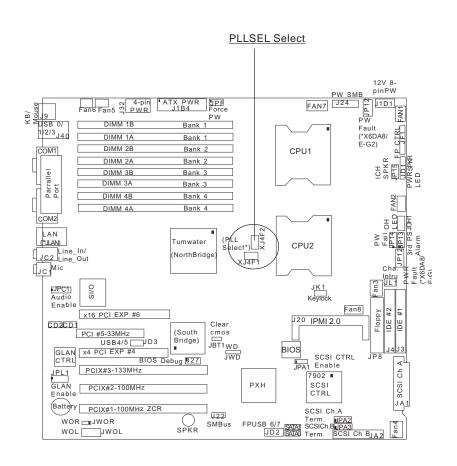
PLLSEL Select (*For XDA8-G/X6DAE-G 0nly)

XJ4F1/XJ4F2 allows the user to select PLLSEL (memory speed). See the table on the right for jumper definitions. (*Default: Closed: 333 MHz)

PLLSEL Select Jumper Settings (XJ4F1/XJ4F2)

DDR	XJ4F1	XJ4F2
*333 MHz	Closed	Closed
266MHz	Open	Open

(*Default:Closed-333MHz)



2-7 Onboard Indicators

GLAN LEDs (*X6DA8/E-G2)

The Gigabit Ethernet LAN ports has two LEDs. The left LED indicates activity while the right LED may be green, amber or off to indicate the speed of the connection. See the table at right for the functions associated with the second LED. (2 GLAN ports on the X6DA8-G2/X6DAE-G2.)

GLAN LEDs (*X6DA8/E-G)

The Gigabit Ethernet LAN ports has two LEDs. The right LED indicates activity while the left LED may be green, amber or off to indicate the speed of the connection. See the table at right for the functions associated with the second LED. (2 GLAN ports on the X6DA8-G2/X6DAE-G2.)

(*X6DA8/E-G2)

Left Right

(Back View)

1 Gb LAN Right LED Indicator (Link LED)

,			
Definition			
10Mb or NC*			
100 Mb			
1 Gb			

NC=No Connections

1 Gb LAN Left LED Indicator(Activity LED)

LED		
Color	Definition	n
Green	10Mb/	
Blinking	100Mb/10	Эb
_		

(*X6DA8/E-G)



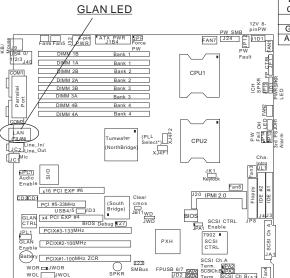
1 Gb LAN Right LED Indicator(Activity LED)

	, , ,
LED	
Color	Definition
Amber	10Mb/
Blinking	100Mb/1Gb
_	

1 Gb LAN Left LED

maioator (Link LLD)		
LED		
Color	Definition	
Off	10Mb or NC*	
Green	100 Mb	
Amber	1 Gb	

NC=No Connections



2-8 Parallel Port, Floppy/Hard Disk Drive and SCSI Connections

Note the following when connecting the floppy and hard disk drive cables:

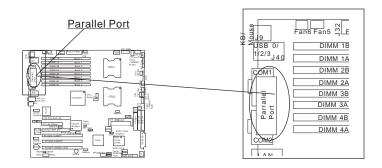
- · The floppy disk drive cable has seven twisted wires.
- A red mark on a wire typically designates the location of pin 1.
- A single floppy disk drive ribbon cable has 34 wires and two connectors to
 provide for two floppy disk drives. The connector with twisted wires always
 connects to drive A, and the connector that does not have twisted wires
 always connects to drive B.

Parallel (Printer) Port Connector

The parallel (printer) port is located on J23. See the table on the right for pin definitions.

Parallel (Printer) Port Pin Definitions

(323)					
Pin Number	Function	Pin Number	Function		
1	Strobe-	2	Auto Feed-		
3	Data Bit 0	4	Error-		
5	Data Bit 1	6	Init-		
7	Data Bit 2	8	SLCT IN-		
9	Data Bit 3	10	GND		
11	Data Bit 4	12	GND		
13	Data Bit 5	14	GND		
15	Data Bit 6	16	GND		
17	Data Bit 7	18	GND		
19	ACK	20	GND		
21	BUSY	22	GND		
23	PE	24	GND		
25	SLCT	26	NC		



Floppy Connector

The floppy connector is located on JP8. See the table below for pin definitions.

Floppy Connector Pin Definitions (J8)

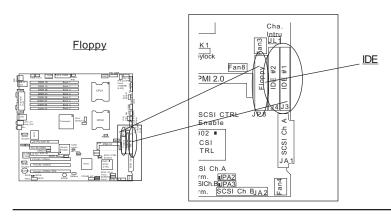
Pin Number	Function	Pin Number	Function
1	GND	2	FDHDIN
3	GND	4	Reserved
5	Key	6	FDEDIN
7	GND	8	Index-
9	GND	10	Motor Enable
11	GND	12	Drive Select B-
13	GND	14	Drive Select A-
15	GND	16	Motor Enable
17	GND	18	DIR-
19	GND	20	STEP-
21	GND	22	Write Data-
23	GND	24	Write Gate-
25	GND	26	Track 00-
27	GND	28	Write Protect-
29	GND	30	Read Data-
31	GND	32	Side 1 Select-
33	GND	34	Diskette

IDE Connectors

There are no jumpers to configure the onboard IDE#1 and #2 connectors (at J3 and J4, respectively). See the table on the right for pin definitions.

IDE Connector Pin Definitions (J3 J4)

Pin Number	Function	Pin Number	Function
1	Reset IDE	2	GND
3	Host Data 7	4	Host Data 8
5	Host Data 6	6	Host Data 9
7	Host Data 5	8	Host Data 10
9	Host Data 4	10	Host Data 11
11	Host Data 3	12	Host Data 12
13	Host Data 2	14	Host Data 13
15	Host Data 1	16	Host Data 14
17	Host Data 0	18	Host Data 15
19	GND	20	Key
21	DRQ3	22	GND
23	I/O Write-	24	GND
25	I/O Read-	26	GND
27	IOCHRDY	28	BALE
29	DACK3-	30	GND
31	IRQ14	32	IOCS16-
33	Addr 1	34	GND
35	Addr 0	36	Addr 2
37	Chip Select 0	38	Chip Select 1-
39	Activity	40	GND

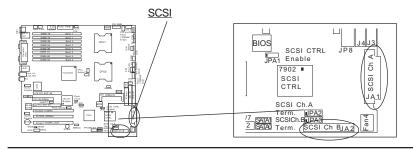


Ultra320 SCSI Connectors (*X6DA8-G/X6DA8-G2 Only)

Refer to the table below for the pin definitions of the Ultra320 SCSI connectors located at JA1, JA2.

68-pin Ultra320 SCSI Connectors (JA1 and JA2)

	-pin Ultra320 SCSI	COI	inectors (JA	1 and JAZ)
Connector Contact			Connector Contact	
Number	Signal Names		Number	Signal Names
1	+DB(12)		35	-DB(12)
2	+DB(13)		36	-DB(13)
3	+DB(14)		37	-DB(14)
4	+DB(15)		38	-DB(15)
5	+DB(P1)		39	-DB(P1)
6	+DB(0)		40	-DB(0)
7	+DB(1)		41	-DB(1)
8	+DB(2)		42	-DB(2)
9	+DB(3)		43	-DB(3)
10	+DB(4)		44	-DB(4)
11	+DB(5)		45	-DB(5)
12	+DB(6)		46	-DB(6)
13	+DB(7)		47	-DB(7)
14	+DB(P)		48	-DB(P)
15	GROUND		49	GROUND
16	DIFFSENS		50	GROUND
17	TERMPWR		51	TERMPWR
18	TERMPWR		52	TERMPWR
19	RESERVED		53	RESERVED
20	GROUND		54	GROUND
21	+ATN		55	-ATN
22	GROUND		56	GROUND
23	+BSY		57	-BSY
24	+ACK		58	-ACK
25	+RST		59	-RST
26	+MSG		60	-MSG
27	+SEL		61	-SEL
28	+C/D		62	-C/D
29	+REQ		63	-REQ
30	+1/0		64	-I/O
31	+DB(8)		65	-DB(8)
32	+DB(0) +DB(9)		66	-DB(0) -DB(9)
33	+DB(3) +DB(10)		67	-DB(9) -DB(10)
34	+DB(10) +DB(11)		68	-DB(10) -DB(11)
34	+55(11)		00	-55(11)



Chapter 3 Troubleshooting

3-1 Troubleshooting Procedures

Use the following procedures to troubleshoot your system. If you have followed all of the procedures below and still need assistance, refer to the 'Technical Support Procedures' and/or 'Returning Merchandise for Service' section(s) in this chapter.

Note: Always disconnect the power cord before adding, changing or installing any hardware components.

Before Power On

- 1. Make sure no short circuits exist between the motherboard and chassis.
- 2. Disconnect all ribbon/wire cables from the motherboard, including those for the keyboard and mouse.
- 3. Remove all add-on cards.
- Install one CPU (making sure it is fully seated) and connect the chassis speaker and the power LED to the motherboard. (Check all jumper settings as well.)
- 5. Use only the correct type of onboard CMOS battery as recommended by the Manufacturer. Do not install the onboard battery upside down to avoid possible explosion.

No Power

- Make sure no short circuits exist between the motherboard and the chassis.
- 2. Verify that all jumpers are set to their default positions.
- 3. Check that the 115V/230V switch on the power supply is properly set.
- 4. Turn the power switch on and off to test the system.
- 5. The battery on your motherboard may be old. Check to verify that it still supplies ~3VDC. If it does not, replace it with a new one.

No Video

- If the power is on but you have no video, remove all the add-on cards and cables.
- Use the speaker to determine if any beep codes exist. Refer to the Appendix for details on beep codes.
- 3. Make sure that memory speeds and jumper settings are set correctly.

(*X6DA8-G/X6DAE-G only)

NOTE

If you are a system integrator, VAR or OEM, a POST diagnostics card is recommended. For I/O port 80h codes, refer to App. B.

Memory Errors

- 1. Make sure the DIMM modules are properly and fully installed.
- Determine if different speeds of DIMMs have been installed and verify that the BIOS setup is configured for the fastest speed of RAM used. It is recommended to use the same RAM speed for all DIMMs in the system.
- Make sure you are using the correct type of Registered, ECC DDR2 400 (PC3200) or DDR 333/266 (PC2700/PC2100) SDRAM (*recommended by the manufacturer.) (*Please refer to Chapter 2 for DDR memory support.)
- Check for bad DIMM modules or slots by swapping a single module between two slots and noting the results.
- Make sure all memory modules are fully seated in their slots. As an interleaved memory scheme is used, you must install two modules at a time, beginning with DIMM #1A, then DIMM #1B, and so on (see Section 2-3).

Losing the System's Setup Configuration

- Ensure that you are using a high quality power supply. A poor quality power supply may cause the system to lose the CMOS setup information. Refer to Section 1-6 for details on recommended power supplies.
- 2. The battery on your motherboard may be old. Check to verify that it still supplies ~3VDC. If it does not, replace it with a new one.
- 3. If the above steps do not fix the Setup Configuration problem, contact your vendor for repairs.

3-2 Technical Support Procedures

Before contacting Technical Support, please take the following steps. Also, note that as a motherboard manufacturer, Super Micro does not sell directly to end-users, so it is best to first check with your distributor or reseller for troubleshooting services. They should know of any possible problem(s) with the specific system configuration that was sold to you.

- Please go through the 'Troubleshooting Procedures' and 'Frequently Asked Question' (FAQ) sections in this chapter or see the FAQs on our web site (http://www.supermicro.com/support/faqs/) before contacting Technical Support.
- 2. BIOS upgrades can be downloaded from our web site at (http://www.supermicro.com/support/bios/).

Note: Not all BIOS can be flashed depending on the modifications to the boot block code.

- 3. If you still cannot resolve the problem, include the following information when contacting Super Micro for technical support:
 - •Motherboard model and PCB revision number
 - •BIOS release date/version (this can be seen on the initial display when your system first boots up)
 - System configuration

An example of a Technical Support form is on our web site at (http://www.supermicro.com/support/contact.cfm).

4. Distributors: For immediate assistance, please have your account number ready when placing a call to our technical support department. We can be reached by e-mail at support@supermicro.com, by phone at: (408) 503-8000, option 2, or by fax at (408)503-8019.

3-3 Frequently Asked Questions

Question: What are the various types of memory that my mother-board can support?

Answer: The X6DA8-G2/X6DAE-G2 has eight 240-pin DIMM slots that support registered ECC DDR2 400 (PC3200) SDRAM modules. However, the X6DA8-G/X6DAE-8 has eight 184-pin DIMM slots that support registered ECC DDR 333/266 (PC2700/PC2100) SDRAM modules. It is strongly recommended that you do not mix memory modules of different speeds and sizes. Please refer to Chapter 2 for instructions on memory support.

Question: How do I update my BIOS?

Answer: It is recommended that you <u>do not</u> upgrade your BIOS if you are experiencing no problems with your system. Updated BIOS files are located on our web site at http://www.supermicro.com. Please check our BIOS warning message and the information on how to update your BIOS on our web site. Also, check the current BIOS revision and make sure it is newer than your BIOS before downloading. (*Note: There is no BIOS Recovery

function available for the motherboard. Should a problem occur after you flash the BIOS, you will need to change the BIOS chip.)

Question: What's on the CD that came with my motherboard?

Answer: The supplied compact disc has quite a few drivers and programs that will greatly enhance your system. We recommend that you review the CD and install the applications you need. Applications on the CD include chipset drivers for Windows and security and audio drivers.

3-4 Returning Merchandise for Service

A receipt or copy of your invoice marked with the date of purchase is required before any warranty service will be rendered. You can obtain service by calling your vendor for a Returned Merchandise Authorization (RMA) number. When returning to the manufacturer, the RMA number should be prominently displayed on the outside of the shipping carton, and mailed prepaid or hand-carried. Shipping and handling charges will be applied for all orders that must be mailed when service is complete.

This warranty only covers normal consumer use and does not cover damages incurred in shipping or from failure due to the alternation, misuse, abuse or improper maintenance of products.

During the warranty period, contact your distributor first for any product problems.

Chapter 4 Phoenix BIOS

4-1 Introduction

This chapter describes the Phoenix BIOS™ Setup utility for the X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2. The Phoenix ROM BIOS is stored in a flash chip and can be easily upgraded using a floppy disk-based program.

Note: Due to periodic changes to the BIOS, some settings may have been added or deleted and might not yet be recorded in this manual. Please refer to the Manual Download area of the Supermicro web site http://www.supermicro.com for any changes to the BIOS that may not be reflected in this manual.

System BIOS

The BIOS is the Basic Input Output System used in all IBM® PC, XT™, AT®, and PS/2® compatible computers. The Phoenix BIOS flash chip stores the system parameters, such type of disk drives, video displays, etc. in the CMOS. The CMOS memory requires very little electrical power. When the computer is turned off, a back-up battery provides power to the CMOS Memory in RTC Logic, enabling it to retain system parameters. Each time the computer is powered-on the computer is configured with the values stored in the CMOS Memory by the system BIOS, which gains control at boot-up.

How To Change the Configuration Data

The CMOS information that determines the system parameters may be changed by entering the BIOS Setup utility. This Setup utility can be accessed by pressing the <Delete> key at the appropriate time during system boot, see below.

Starting the Setup Utility

Normally, the only visible POST (Power On Self Test) routine is the memory test. As the memory is being tested, press the <Delete> key to enter the main menu of the BIOS Setup utility. From the main menu, you can access the other setup screens, such as the Security and Power menus. Beginning with Section 4-3, detailed descriptions are given for each parameter setting in the Setup utility.

4-2 Running Setup

*Default settings are in bold text unless otherwise noted.

The BIOS setup options described in this section are selected by choosing the appropriate text from the main BIOS Setup screen. All displayed text is described in this section, although the screen display is often all you need to understand how to set the options (see on next page).

When you first power on the computer, the Phoenix BIOS™ is immediately activated.

While the BIOS is in control, the Setup program can be activated in one of two ways:

- 1. By pressing <Delete> immediately after turning the video on, or
- 2. When the message shown below appears briefly at the bottom of the screen during the POST (Power On Self-Test), press the <Delete> key to activate the main Setup menu:

Press the <Delete> key to enter Setup

4-3 Main BIOS Setup

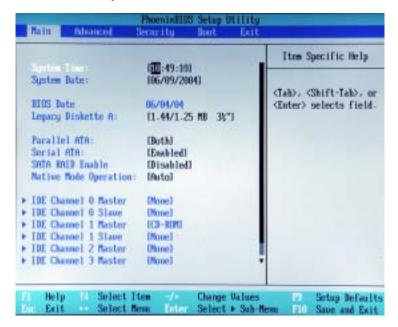
All main Setup options are described in this section. The main BIOS Setup screen is displayed below.

Use the Up/Down arrow keys to move among the different settings in each menu. Use the Left/Right arrow keys to move among the different setup screens.

Press the <Esc> key to exit the CMOS Setup Menu or a submenu. The next section describes in detail how to navigate through the menus. Press <+> and <-> keys to change the value of a setting.

Items that use submenus are indicated with the icon. With the item highlighted, press the <Enter> key to access the submenu.

Main BIOS Setup Menu



Main Setup Features

System Time

To set the system date and time, key in the correct information in the appropriate fields. Then press the <Enter> key to save the data.

System Date

Using the arrow keys, highlight the month, day and year fields and enter the correct data. Press the <Enter> key to save the data.

BIOS Date

This feature allows the BIOS to automatically display the date when the present BIOS was built. This is used to identify the release version of the current BIOS.

Legacy Diskette A

This setting allows the user to set the type of floppy disk drive installed as diskette A. The options are Disabled, 360Kb 5.25 in, 1.2MB 5.25 in, 720Kb 3.5 in, 1.44/1.25MB, 3.5 in and 2.88MB 3.5 in.

Parallel ATA

This setting allows the user to enable or disable the funciton of IDE Channels. The options are Disabled, Channel 0, Channel 1 and **Both.**

Serial ATA

This setting allows the user to enable or disable the function of Serial ATA. The options are Disabled and **Enabled.**

Serial ATA RAID Enable

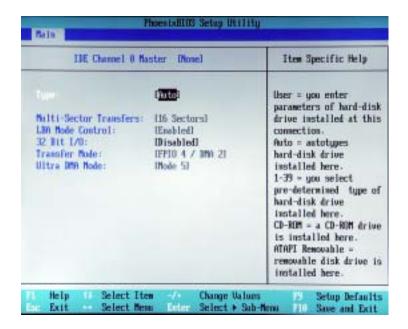
Select Enable to enable Serial ATA RAID Functions. (*For the Windows OS environment, use the RAID driver if this feature is set to Enabled. If **Disabled**, no drivers are needed.)

Native Mode Operation

This option allows the user to select the Native Mode for ATA. Some Operating Systems are not supported by the Native Mode. The options are: Serial ATA, Parallel ATA, **Auto**, and Both.

▶IDE Channel 0 Master/Slave, IDE Channel 1 Master/Slave, IDE Channel 2 Master, IDE Channel 3 Master

These settings allow the user to set the parameters of IDE Channel 0 Master/Slave, IDE Channel 1 Master/Slave, IDE Channel 2 Master, IDE Channel 3 Master slots. Hit <Enter> to activate the following sub-menu screen for detailed options of these items. Set the correct configurations accordingly. The items included in the sub-menu are:



Type

Selects the type of IDE hard drive. The options are **Auto** (allows the BIOS to automatically determine the hard drive's capacity, number of heads, etc.), a number from 1-39 to select a predetermined type of hard drive, CD-ROM and ATAPI Removable. The option- "User" will allow the user to enter the parameters of the HDD installed at this connection. The option-"Auto" will allow the BIOS to automatically configure the parameters of the HDD installed at the connection. Choose the option"1-39" to select a pre-determined HDD type. Select CD-ROM if a CD-ROM drive is installed. Select ATAPI if a removable disk drive is installed.

Multi-Sector Transfers

Select the number of transfer sectors. The options are Disabled, 2, 4, 6, 8 and 16 Sectors.

LBA (Large Block Addressing) Mode Control

If set to enabled, this feature allows a PC computer to access hard disk drives larger than 528MB. The options are Disabled and **Enabled**.

32 Bit I/O

This option allows the user to enable or disable the function of 32-bit datea transfer. The options are Enabled and **Disabled**.

Transfer Mode

Selects the transfer mode. The options are **Standard**, Fast PIO1, Fast PIO2, Fast PIO3, Fast PIO4, FPIO3/DMA1 and FPIO4/DMA2.

Ultra DMA (Direct Memory Access) Mode

This feature allows the user to select Ultra DMA Modes. DMA Modes allow peripheral devices (such as souond cards, floppy disks) transfer data directly to and from memory without going through the CPU. With double transition clocking, UDMA (Ultra DMA) allows data to be transferred on both the rising and the falling edges of the clock, doubling data throughput for any given clock speed. The options are Disabled, Mode 0, Mode 1, Mode 2, Mode 3, Mode 4, and Mode 5. Please refer to the table below for detailed infomation. Selects Ultra DM A Mode. The options are **Disabled**, Mode 0, Mode 1, Mode 2, Mode 3, Mode 4 and Mod5.

Ultra DMA Mode	Cycle Time (Nanoseconds)	Maximum Transfer Rate (MB/s)
Mode 0	240	16.7
Mode 1	160	25.0
Mode 2	120	33.3
Mode 3	90	44.4
Mode 4	60	66.7
Mode 5	40	100

System Memory

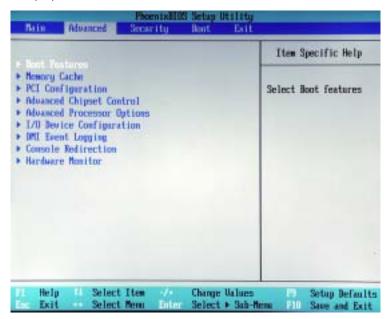
This display informs you how much system memory is recognized as being present in the system.

Extended Memory

This display informs you how much extended memory is recognized as being present in the system.

4-4 Advanced Setup

Choose Advanced from the Phoenix BIOS Setup Utility main menu with the arrow keys. You should see the following display. The items with a triangle beside them have sub menus that can be accessed by highlighting the item and pressing <Enter>. Options for PIR settings are displayed by highlighting the setting option using the arrow keys and pressing <Enter>. All Advanced BIOS Setup options are described in this section.



▶Boot Features

Access the submenu to make changes to the following settings.

Quick Boot Mode

If enabled, this feature will speed up the POST (Power On Self Test) routine by skipping certain tests after the computer is turned on. The settings are **Enabled** and Disabled. If Disabled, the POST routine will run at normal speed.

Quiet Boot

When Enabled, the system will switch to the graphic mode and display OEM's logo during boot-up. The system will automatically switch to the text mode if an error occurs. The settings are **Enabled** and Disabled.

ACPI Mode

Use the setting to determine if you want to employ ACPI (Advanced Configuration and Power Interface) power management on your system. The options are **Yes** and No.

ACPI Sleep Mode

Selects the sleep mode for ACPI. The options are **S1(-Stanby)** and S3 (-Suspend to RAM).

Power Button Behavior

This setting allows you to choose how the system powers down when the user presses the power button. Select Instant-Off to power off the system as soon as the power button is pressed. Select 4-sec override to allow the system to wait for 4 seconds before power-off when the power button is pressed. The options are **Instant-Off** and 4-sec override.

Keyboard on Now Function

This option allows you to select how the system may be resumed from the S3-S5 state. The options are Space (by pressing the sapce bar), Password (by entering a password), and **Disabled**.

Power Loss Control

This setting allows you to choose how the system will react when power returns after an unexpected loss of power. The options are Stay Off, Power On and Last State.

Watch Dog

This setting is for enabling the Watch Dog feature. The The options are Enabled and **Disabled**.

Summary Screen

This setting allows you to **Enable** or Disable the summary screen which displays the system configuration during bootup.

▶Memory Cache

Cache System BIOS Area

This setting allows you to designate a reserve area in the system memory to be used as a System BIOS buffer to allow the BIOS to write (cache) its data into this reserved memory area. Select "Write Protect" to enable this function, and this area will be reserved for the BIOS ROM access only. Select "Uncached" to disable this function and make this area available for other devices.

Cache Video BIOS Area

This setting allows you to designate a reserve area in the system memory to be used as a Video BIOS buffer to allow the BIOS to write (cache) its data into this reserved memory area. Select "Write Protect" to enable the function and this area will be reserved for the BIOS ROM access only. Select "Uncached" to disable this function and make this area available for other devices.

Cache Base 0-512K

If enabled, this feature will allow the data stored in the base memory area of Block 0-512K to be cached (written) into the system memory or into L1, L2, L3 cache area inside the CPU to speed up CPU operations. Select "Uncached" to disable this function. Select "Write Through" to allow data to be cached into the system memory and into L1, L2, L3 cache area of the CPU at the same time. Select "Write Protect" to prevent data from being cached into the system memory area of Block 0-512K. Select "Write Back" to allow CPU to write data back directly from the L1, L2, L3 cache inside the CPU without writing data to the System Memory for fast CPU data processing and operation. The options are "Uncached", "Write Through", "Write Protect", and "Write Back".

Cache Base 512K-640K

If enabled, this feature will allow the data cached in the memory area of Blcok 512K-640K or to into L1, L2, L3 cache inside the CPU to speed up CPU operations. Select "Uncached" to disable this function. Select "Write Through" to allow data to be cached into the CPU L1, L2, L3 cache area and into the system memory at the same time. Select "Write Protect" to prevent data from being written into the base memory area of Block 512K-640K. Select "Write Back" to allow CPU to write data back directly from L1, L2, L3 Cache area inside the CPU without writing data to the System Memory for fast CPU data processing and operation. The options are "Uncached", "Write Through", "Write Protect", and "Write Back".

Cache Extended Memory

If enabled, this feature will allow the data cached in the system memory area above 1 MB or to be cached into L1, L2, L3 cache inside the CPU to speed up CPU operations. Select "Uncached" to disable this function. Select "Write Through" to allow data to be cached into the system memory and into L1, L2, L3 cache area in the CPU at the same time. Select "Write Protect" to prevent data from being written into the system memory above 1MB. Select "Write Back" to allow the CPU to write data back directly from L1, L2, L3 Cache area inside the CPU without writing data to the System Memory for fast CPU data processing and operation. The options are "Uncached", "Write Through", "Write Protect", and "Write Back".

▶PCI Configuration

Access the submenu to make changes to the following settings for PCI devices.

Onboard GLAN (Gigabit-LAN) OPROM Configure

Enabling this option provides the capability to boot from GLAN. The options are Enabled and **Disabled**.

Onboard SCSI OPROM Configure

Enabling this option provides the caability to boot from SCSI HDD. The options are Disabled and **Enabled**.

Reset Configuration Data

If set to Yes, this setting clears the Extended System Configuration Data-(ESCD) area. The options are Yes and **No**.

Frequency for PCIX#1-#2/SCSI

This option allows the user to change the bus frequency for the devices installed in the slot indicated. The options are **Auto**, PCI 66 MHz, PCI-X 66 MHz, PCI-X 100 MHz, and PCI-X 133 MHz.

Frequency for PCIX#3/G-LAN

This option allows the user to change the bus frequency of the devices installed in the slot indicated. The options are **Auto**, PCI 66 MHz, PCI-X 66 MHz, PCI-X 100 MHz, and PCI-X 133 MHz.

▶PCI-X 100MHz ZCR Slot#1/PCI-X 100MHz Slot#2/PCI-X 133MHz Slot#3/PCI-E X4 Slot#4/PCI 33MHz Slot#5/PCI-E X16 Slot#6

Access the submenu for each of the settings above to make changes to the following:

Option ROM Scan

When enabled, this setting will initialize the device expansion ROM. The options are **Enabled** and Disabled.

Enable Master

This setting allows you to enable the selected device as the PCI bus master. The options are **Enabled** and Disabled.

Latency Timer

This setting allows you to set the clock rate for Bus Master. A high-prioity, high-throughout device may benefit from a greater Clock rate. The options are **Default**, 0020h, 0040h, 0060h, 0080h, 00A0h, 00C0h, and 00E0h. For Unix, Novell and other Operating Systems, please select the option: "Other". If a drive fails after the installation of a new software, you might want to change this settiing and try again. Different OS requires different Bus Master clock rate.

Large Disk Access Mode

This setting determines how large hard drives are to be accessed. The options are **DOS** or Other (for Unix, Novellle NetWare and other operating systems).

► Advanced Chipset Control

Access the submenu to make changes to the following settings.

Force Compliance Mode

If enabled, this feature sets the device specified to comply with the PCI-Express Compliance 1.0 Mode. The options are: **Disabled** and Enabled.

Memory RAS Feature Control

Select this option to enable Memory RAS (Reliability/ Availability/ Serviceability) Feature Control. The Options are **Standard**, Sparing, and Mirroring. Select Sparing (RAID 0) to increase the performance of data transfer by simultaneously writing data to two drives. Select Mirroring (RAID 1) to increase data protection by writing identical data on two drives.

Clock Spectrum Feature

If "Enabled", BIOS will sensor and attempt to reduce the Electromagnetic Interference caused by the components. The options are Enabled and **Disabled**.

DRAM Data Integrity Mode

Select this option to increase the integrity and accuracy of Data stored in DRAM. The options are 72-bit ECC, 144-bit ECC, Auto, Algorithms and Disabled.

ECC Error Type

This setting lets you select which type of interrupt to be activated as a result of an ECC error. The options are **None**, NMI (Non-Maskable Interrupt), SMI (System Management Interrupt) and SCI (System Control Interrupt.)

SERR (System Error) Signal Condition

This setting specifies the conditions required to be qualified as an ECC error. The options are None, **Single Bit**, Multiple Bit and Both.

USB Function

This setting allows you to **Enable** or Disable all functions for the USB devices specified.

Legacy USB Support

This setting allows you to enable support for Legacy USB devices. The settings are **Enabled** and Disabled.

► Advanced Processor Options

Access the submenu to make changes to the following settings.

CPU Speed

This is a display that indicates the speed of the installed processor.

Hyper-threading

This setting allows you to **Enable** or Disable the function of hyper-threading. Enabling hyper-threading results in increased CPU performance.

Machine Checking

This setting allows you to enable or disable Machine Checking. When set to Enabled, the OS will debug the system during system reset after a system crash. The options are **Disabled** or Enabled.

Adjacent Cache Line Prefetch

The CPU fetches the cache line for 64 bytes if this option is set to Disabled. The CPU fetches both cache lines for 128 bytes as comprised if Enabled. The options are Disabled and **Enabled**.

►I/O Device Configuration

Access the submenu to make changes to the following settings.

KBC Clock input

This setting allows you to set the clock frequency for the Keyboard Clock. The options are 6MHz, 8MHz, and 12 MHz.

Onboard COM1

This setting allows you to assign control of serial port A. The options are **Enabled** (user defined), Disabled, Auto (BIOS controlled) and OS Controlled.

Base I/O Address

Select the base I/O address for serial port A. The options are **3F8**, 2F8, 3E8 and 2E8.

Interrupt

Select the IRQ (interrupt request) for the parallel port. The options are IRQ3 and IRQ4.

Onboard COM2

This setting allows you to assign control of serial port B. The options are **Enabled** (user defined), Disabled, Auto (BIOS controlled) and OS Controlled.

Mode

Specify the type of device that will be connected to serial port B. The options are **Normal**, IR (for an infrared device) and ASK-IR.

Base I/O Address

Select the base I/O address for serial port B. The options are 3F8, **2F8**, 3E8 and 2E8.

Interrupt

Select the IRQ (interrupt request) for the parallel port. The options are IRQ3 and IRQ4.

Parallel Port

This setting allows you to assign control of the parallel port. The options are **Enabled** (user defined), Disabled and Auto (BIOS controlled).

Base I/O Address

Select the base I/O address for the parallel port. The options are $\bf 378$, $\bf 278$ and $\bf 3BC$.

Interrupt

Select the IRQ (interrupt request) for the parallel port. The options are IRQ5 and IRQ7.

Mode

Specify the parallel port mode. The options are Output, Bi-directional, **ECP** and EPP.

DMA Channel

Specify the DMA channel. The options are DMA1 and DMA3.

Floppy Disk Controller

This setting allows you to assign control of the floppy disk controller. The options are **Enabled** (user defined), Disabled, Auto (BIOS controlled) and OS Controlled.

Base I/O Address

Select the base I/O address for the Floppy port. The options are **Primary** and Secondary.

▶DMI Event Logging

Access the submenu to make changes to the following settings.

Event Log Validity

This is a display, not a setting, informing you of the event log validity.

Event Log Capacity

This is a display, not a setting, informing you of the event log capacity.

View DMI Event Log

Highlight this item and press <Enter> to view the contents of the event log.

Event Logging

This setting allows you to Enable or Disable event logging.

ECC Event Logging

This setting allows you to Enable or Disable ECC event logging.

Mark DMI Events as Read

Highlight this item and press <Enter> to mark the DMI events as read.

Clear All DMI Event Logs

Select Yes and press <Enter> to clear all DMI event logs.

▶Console Redirection

Access the submenu to make changes to the following settings.

COM Port Address

Specifies to redirect the console to On-board COM A or On-board COM B. This setting can also be **Disabled**.

BAUD Rate

Select the BAUD rate for console redirection. The options are 300, 1200, 2400, 9600, 19.2K, 38.4K, 57.6K and 115.2K.

Console Type

Choose from the available options to select the console type for console redirection. The options are VT100, VT100,8bit, PC-ANSI, 7bit, **PC ANSI**, VT100+, VT-UTF8.

Flow Control

Choose from the available options to select the flow control for console redirection. The options are: None, XON/XOFF, and CTS/RTS.

Console Connection

Select the console connection: either Direct or Via Modem.

Continue CR after POST

Choose whether to continue with console redirection after the POST routine. The options are On and ${\it Off}$.

► Hardware Monitor Logic

CPU Temperature Threshold

This option allows the user to set a CPU temperature threshold that will activate the alarm system when the CPU temperature reaches this pre-set temperature threshold. The options are 85°C, 90°C, 95°C and 100°C.

Highlight this and hit <Enter> to see monitor data for the following items:

CPU1 Temperature: This item displays CPU1 Temperature.

CPU2 Temperature: This item displays CPU2 Temperature.

System Temperature: This item displays the system Temperature.

Fan Speed Control Modules:

This feature allows the user to decide how the system controls the speeds of the onboard fans. If the option is set to "3-pin fan", the fan speed is controlled based upon the CPU die temperature. When the CPU die temperature is higher, the fan speed will be higher as well. If the option is set to "4-pin", the fan speed will be controlled by the Thermal Management Settings pre-configured by the user at this feature. Select "3-pin" if your chassis came with 3-pin fan headers. Select "4-pin" if your chassis came with 4-pin fan headers. Select "Workstation" if your system is used as a Workstation. Select "Server" if your system is used as a Server. Select "Disable" to disable the fan speed control function to allow the onboard fans to run at the full speed (12V) at all time. The Options are: 1. Disable, 2. 3-pin (Server), 3. 3-pin (Workstation), 4. 4-pin (Server), 5. 4-pin (Workstation).

You can connfigure the desired Fan Speed Control Settings for the following fans:

Fan 1 to Fan 6 (chassis fans), Fan 7 (CPU Fan 1), Fan 8 (CPU Fan2).

The voltage status of the following items will be displayed:

Vcore A

Vcore B

P3V3

P5V

N₁₂V

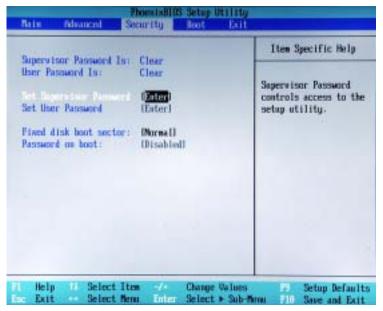
P12V

VDD

P5Vsb

4-5 Security

Choose Security from the Phoenix BIOS Setup Utility main menu with the arrow keys. You should see the following display. Security setting options are displayed by highlighting the setting using the arrow keys and pressing <Enter>. All Security BIOS settings are described in this section.



Supervisor Password Is:

This displays whether a supervisor password has been entered for the system. Clear means such a password has not been used and Set means a supervisor password has been entered for the system.

User Password Is:

This displays whether a user password has been entered for the system. Clear means such a password has not been used and Set means a user password has been entered for the system.

Set Supervisor Password

When the item "Set Supervisor Password" is highlighted, hit the <Enter> key. When prompted, type the Supervisor's password in the dialogue box to set or to change supervisor's password, which allows access to the BIOS.

Set User Password

When the item "Set User Password" is highlighted, hit the <Enter> key. When prompted, type the user's password in the dialogue box to set or to change the user's password, which allows access to the system at bootup.

Fixed Disk Boot Sector

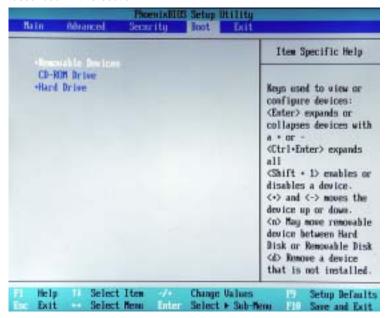
This setting may offer some protection against viruses when set to Write Protect, which protects the boot sector on the hard drive from having a virus written to it. The other option is **Normal**.

Password on Boot

This setting allows you to require a password to be entered when the system boots up. The options are Enabled (password required) and Disabled (password not required).

4-6 Boot

Choose Boot from the Phoenix BIOS Setup Utility main menu with the arrow keys. You should see the following display. Highlighting a setting with a + or - will expand or collapse that entry. See details on how to change the order and specs of boot devices in the Item Specific Help window. All Boot BIOS settings are described in this section.



+Removable Devices

Highlight and press <Enter> to expand the field. See details on how to change the order and specs of devices in the Item Specific Help window.

CD-ROM Drive

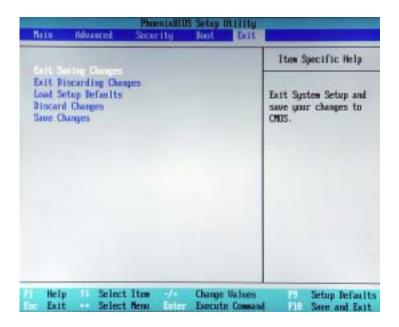
See details on how to change the order and specs of the CD-ROM drive in the Item Specific Help window.

+Hard Drive

Highlight and press <Enter> to expand the field. See details on how to change the order and specs of hard drives in the Item Specific Help window.

4-7 Exit

Choose Exit from the Phoenix BIOS Setup Utility main menu with the arrow keys. You should see the following display. All Exit BIOS settings are described in this section.



Exit Saving Changes

Highlight this item and hit <Enter> to save any changes you made and to exit the BIOS Setup utility.

Exit Discarding Changes

Highlight this item and hit <Enter> to exit the BIOS Setup utility without saving any changes you may have made.

Load Setup Defaults

Highlight this item and hit <Enter> to load the default settings for all items in the BIOS Setup. These are the safest settings to use.

Discard Changes

Highlight this item and hit <Enter> to discard (cancel) any changes you made. You will remain in the Setup utility.

Save Changes

Highlight this item and hit <Enter> to save any changes you made. You will remain in the Setup utility.

Notes

Appendix A BIOS POST Codes

This section lists the POST (Power On Self Test) codes for the PhoenixBIOS. POST codes are divided into two categories: recoverable and terminal.

Recoverable POST Errors

When a recoverable type of error occurs during POST, the BIOS will display an POST code that describes the problem. BIOS may also issue one of the following beep codes:

- 1 long and two short beeps video configuration error
- 1 continuous long beep no memory detected

Terminal POST Errors

If a terminal type of error occurs, BIOS will shut down the system. Before doing so, BIOS will write the error to port 80h.

The following is a list of codes that may be written to port 80h.

POST Code	Description		
02h	Verify Real Mode		
03h	Disable Non-Maskable Interrupt (NMI)		
04h	Get CPU type		
06h	Initialize system hardware		
07h	Disable shadow and execute code from the ROM.		
08h	Initialize chipset with initial POST values		
09h	Set IN POST flag		
0Ah	Initialize CPU registers		
0Bh	Enable CPU cache		
0Ch	Initialize caches to initial POST values		
0Eh	Initialize I/O component		
0Fh	Initialize the local bus IDE		
10h	Initialize Power Management		
11h	Load alternate registers with initial POST values		
12h	Restore CPU control word during warm boot		
13h	Initialize PCI Bus Mastering devices		
14h	Initialize keyboard controller		
16h	1-2-2-3 BIOS ROM checksum		
17h	Initialize cache before memory Auto size		

POST Code	Description	
18h	8254 timer initialization	
1Ah	8237 DMA controller initialization	
1Ch	Reset Programmable Interrupt Controller	
20h	1-3-1-1 Test DRAM refresh	
22h	1-3-1-3 Test 8742 Keyboard Controller	
24h	Set ES segment register to 4 GB	
28h	Auto size DRAM	
29h	Initialize POST Memory Manager	
2Ah	Clear 512 kB base RAM	
2Ch	1-3-4-1 RAM failure on address line xxxx*	
2Eh	1-3-4-3 RAM failure on data bits xxxx * of low byte of	
	memory bus	
2Fh	Enable cache before system BIOS shadow	
32h	Test CPU bus-clock frequency	
33h	Initialize Phoenix Dispatch Manager	
36h	Warm start shut down	
38h	Shadow system BIOS ROM	
3Ah	Auto size cache	
3Ch	Advanced configuration of chipset registers	
3Dh	Load alternate registers with CMOS values	
41h	Initialize extended memory for RomPilot	
42h	Initialize interrupt vectors	
45h	POST device initialization	
46h	2-1-2-3 Check ROM copyright notice	
47h	Initialize I20 support	
48h	Check video configuration against CMOS	
49h	Initialize PCI bus and devices	
4Ah	Initialize all video adapters in system	
4Bh	QuietBoot start (optional)	
4Ch	Shadow video BIOS ROM	
4Eh	Display BIOS copyright notice	
4Fh	Initialize MultiBoot	
50h	Display CPU type and speed	
51h	Initialize EISA board	
52h	Test keyboard	
54h	Set key click if enabled	
55h	Enable USB devices	
58h	2-2-3-1 Test for unexpected interrupts	
59h	Initialize POST display service	
5Ah	Display prompt "Press F2 to enter SETUP"	
5Bh	Disable CPU cache	

POST Code	Description		
5Ch	Test RAM between 512 and 640 kB		
60h	Test extended memory		
62h	Test extended memory address lines		
64h	Jump to UserPatch1		
66h	Configure advanced cache registers		
67h	Initialize Multi Processor APIC		
68h	Enable external and CPU caches		
69h	Setup System Management Mode (SMM) area		
6Ah	Display external L2 cache size		
6Bh	Load custom defaults (optional)		
6Ch	Display shadow-area message		
6Eh	Display possible high address for UMB recovery		
70h	Display error messages		
72h	Check for configuration errors		
76h	Check for keyboard errors		
7Ch	Set up hardware interrupt vectors		
7Dh	Initialize Intelligent System Monitoring		
7Eh	Initialize coprocessor if present		
80h	Disable onboard Super I/O ports and IRQs		
81h	Late POST device initialization		
82h	Detect and install external RS232 ports		
83h	Configure non-MCD IDE controllers		
84h	Detect and install external parallel ports		
85h	Initialize PC-compatible PnP ISA devices		
86h	Re-initialize onboard I/O ports.		
87h	Configure Motherboard Configurable Devices		
	(optional)		
88h	Initialize BIOS Data Area		
89h	Enable Non-Maskable Interrupts (NMIs)		
8Ah	Initialize Extended BIOS Data Area		
8Bh	Test and initialize PS/2 mouse		
8Ch	Initialize floppy controller		
8Fh	Determine number of ATA drives (optional)		
90h	Initialize hard-disk controllers		
91h	Initialize local-bus hard-disk controllers		
92h	Jump to UserPatch2		
93h	Build MPTABLE for multi-processor boards		
95h	Install CD ROM for boot		
96h	Clear huge ES segment register		
97h	Fix up Multi Processor table		
98h	1-2 Search for option ROMs. One long, two short		
	beeps on checksum failure		

POST Code 99h Check for SMART Drive (optional) 9Ah Shadow option ROMs 9Ch Set up Power Management 9Dh Initialize security engine (optional) 9Eh Enable hardware interrupts	
9Ah Shadow option ROMs 9Ch Set up Power Management 9Dh Initialize security engine (optional)	
9Ch Set up Power Management 9Dh Initialize security engine (optional)	
9Dh Initialize security engine (optional)	
9Fh Determine number of ATA and SCSI drives	
A0h Set time of day	
A2h Check key lock	
A4h Initialize typematic rate	
A8h Erase F2 prompt	
AAh Scan for F2 key stroke	
ACh Enter SETUP	
AEh Clear Boot flag	
B0h Check for errors	
B1h Inform RomPilot about the end of POST.	
B2h POST done - prepare to boot operating system	
B4h 1 One short beep before boot	
B5h Terminate QuietBoot (optional)	
B6h Check password (optional)	
B7h Initialize ACPI BIOS	
B9h Prepare Boot	
BAh Initialize SMBIOS	
BBh Initialize PnP Option ROMs	
BCh Clear parity checkers	
BDh Display MultiBoot menu	
BEh Clear screen (optional)	
BFh Check virus and backup reminders	
C0h Try to boot with INT 19	
C1h Initialize POST Error Manager (PEM)	
C2h Initialize error logging	
C3h Initialize error display function	
C4h Initialize system error handler	
C5h PnPnd dual CMOS (optional)	
C6h Initialize note dock (optional)	
C7h Initialize note dock late	
C8h Force check (optional)	
C9h Extended checksum (optional)	
CAh Redirect Int 15h to enable remote keyboard	
CBh Redirect Int 13h to Memory Technologies	
Devices such as ROM, RAM, PCMCIA, and	
serial disk	
CCh Redirect Int 10h to enable remote serial video	

CDh Re-map I/O and memory for PCMCIA
CEh Initialize digitizer and display message

D2h Unknown interrupt

The following are for boot block in Flash ROM

POST Code	Description
E0h	Initialize the chipset
E1h	Initialize the bridge
E2h	Initialize the CPU
E3h	Initialize system timer
E4h	Initialize system I/O
E5h	Check force recovery boot
E6h	Checksum BIOS ROM
E7h	Go to BIOS
E8h	Set Huge Segment
E9h	Initialize Multi Processor
EAh	Initialize OEM special code
EBh	Initialize PIC and DMA
ECh	Initialize Memory type
EDh	Initialize Memory size
EEh	Shadow Boot Block
EFh	System memory test
F0h	Initialize interrupt vectors
F1h	Initialize Run Time Clock
F2h	Initialize video
F3h	Initialize System Management Manager
F4h	Output one beep
F5h	Clear Huge Segment
F6h	Boot to Mini DOS
F7h	Boot to Full DOS

^{*} If the BIOS detects error 2C, 2E, or 30 (base 512K RAM error), it displays an additional word-bitmap (xxxx) indicating the address line or bits that failed. For example, "2C 0002" means address line 1 (bit one set) has failed. "2E 1020" means data bits 12 and 5 (bits 12 and 5 set) have failed in the lower 16 bits. The BIOS also sends the bitmap to the port-80 LED display. It first displays the checkpoint code, followed by a delay, the high-order byte, another delay, and then the loworder byte of the error. It repeats this sequence continuously.

Notes

Appendix B

Installing Software Drivers and Windows Operating System

After all the hardware has been installed, you must first configure the Adaptec Embedded Serial ATA RAID Driver before you install the Windows operating system. The necessary drivers are all included on the Supermicro bootable CDs that came packaged with your motherboard.

B-1 Introduction to the Adaptec Embedded Serial ATA RAID Controller Driver

Serial ATA (SATA)

Serial ATA(SATA) is a physical storage interface. It uses a single cable with a minimum of four wires to create a point-to-point connection between devices. It is a serial link which supports SATA Transfer rates from 150MBps. Because the serial cables used in SATA are thinner than the traditional cables used in Parallel ATA(PATA), SATA systems have better airflow and can be installed in smaller chassis than Parallel ATA. In addition, the cables used in PATA can only extend to 40cm long, while Serial ATA cables can extend up to one meter. Overall, Serial ATA provides better functionality than Parallel ATA.

Introduction to the Intel ICH5R I/O Controller Hub

Located in the South Bridge of the Intel E7525 (Tumwater)Chipset, the ICH5R I/O Controller Hub provides the I/O subsystem with access to the rest of the system. It supports 2-channel Ultra ATA/100 Bus Master IDE controller (PATA) and two Serial ATA (SATA) Host Controllers, which support up to two Serial ATA ports and up to two RAID drives.

Configuring BIOS settings for the SATA RAID Functions

1. Press the key during system bootup to enter the BIOS Setup Utility.

(*Note: If it is the first time to power on the system, we recommend that you load the Optimized Default Settings. If you have already done so, please skip to Step 3.

- 2. Use the arrow keys to select the "Exit" Menu. Once in the "Exit" Menu, scroll down the menu to select the item- "Load Optimized Default settings" and press the <Enter> key. Select "OK" to confirm the selection. Press the <Enter> key to load the default settings to the BIOS.
- 3. Use the arrow keys to select the "Main" Menu in the BIOS.
- 4. Scroll down to the next item-"SATA RAID Enable", select "Enabled" and press <Enter>.
- 5. Tap the <Esc> key and scroll down to "Exit". Select "Save and Exit" from the "Exit" menu. Press the <Enter> key to save the changes and exit the BIOS.
- 6. Once you've exited the BIOS Utility, the system will re-boot.
- 7. During the system startup, press the <Ctrl> and the <A> keys simultaneously to run the Adaptec RAID Configuration Utility when prompted by the following message:

Press <Ctrl><A> for Adaptec RAID Configuration Utility

The Adaptec Embedded Serial ATA with HostRAID Controller Driver

Adaptec's Embedded Serial ATA RAID with HostRAID controller adds RAID functionality to the Serial ATA I/O controller by supporting RAID 0 (Striping) or RAID 1 (Mirroring) to enhance the industry's pioneer PCI-to-e host controller products. RAID striping (RAID 0) can greatly improve hard disk I/O performance because of its capability in striping data across multiple drives. RAID mirroring (RAID 1) allows the data to be simultaneously written to two drives, so critical data is always available even if a single hard disk fails. Due to the built-in functionality, the X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2 is specially designed to keep pace with the increasing performance demands of computer systems by improving disk I/O throughput and providing data accessibility regardless of a single disk failure. By incorporating the Adaptec Embedded Serial ATA into the motherboard design, Supermicro's X6DA8-G/X6DAE-G/X6DA8-G2/X6DAE-G2 offers the user with the benefits of SATARAID without the high costs associated with hardware RAID applications.

(*Note: For Adaptec's RAID Driver Installation Instructions, please refer to the Adaptec RAID Controller User's Guide: "Emb_SA_RAID_UG.pdf" in the CD that came with this motherboard. You can also download a copy of Adaptec's User's Guide from our web site at www.supermicro.com.)

Using the Adaptec RAID Configuration Utility (ARC)

The Adaptec RAID Configuration Utility is an embedded BIOS Utility, including:

*Array Configuration Utility: Use this utility when you want to create, configure and manage arrays.

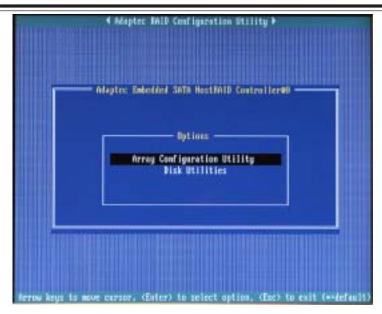
* Disk Utilities: Use this option to format or verify disks.

To run the Adaptec RAID Configuration Utility, you will need to enable the RAID function in the system BIOS (refer to Chapter 4 for System BIOS Configurations), and then, press the <Ctrl> and <A> keys simultaneously when prompted to do so during the system startup. (Refer to the previous page for detailed instructions.)

(*Note: To select an option, use the arrow keys to highlight the item and then press the <Enter> key to select it. To return to the previous menu, press the <ESC> key.)

A. Using the Array Configuration Utility (ACU)

The Array Configuration Utility (ACU) enables you to create, manage, and delete arrays from the controller's BIOS, add and delete spare drives, and initialize drives. During the system startup, press <Ctrl> and <A> key simultaneously, and the main menu will appear.



Managing Arrays

Select this option to view array properties, and delete arrays. The following sections describe the operations Of "Managing Arrays".

To select this option, use the arrow keys and the <enter> key to select "Managing Arrays" from the main menu (as shown above).



Viewing Array Properties

To view the properties of an existing array:

- 1. At the BIOS prompt, press Ctrl+A.
- 2. From the ARC menu, select Array Configuration Utility (ACU).
- 3. From the ACU menu, select Manage Arrays (as shown on the previous screen.)
- **4.** From the List of Arrays dialog box, select the array you want to view and press **Enter**.

The Array Properties dialog box appears, showing detailed information on the array. The physical disks associated with the array are displayed here.

5. Press Esc to return to the previous menu.

Deleting Arrays

*Warning: Back up the data on an array before you delete it to prevent the loss of data. Deleted arrays cannot be restored.

To delete an existing array:

- 1. Turn on your computer and press Ctrl+A when prompted to access the ARC utility.
- 2. From the ARC main menu, select Array Configuration Utility (ACU).
- 3. From the ACU menu, select Manage Arrays.
- 4. Select the array you wish to delete and press Delete.
- **5.** In the Array Properties dialog box, select **Delete** and press **Enter**. The following prompt is displayed:

*Warning!! Deleting the array will render array unusable. Do you want to delete the array?(Yes/No):

RAID 1 only—the following prompt is also displayed:

Deleting the partition will result in data loss! Do you also want to delete the partition? (Yes/No):

- **6.** Press **Yes** to delete the array or partition or **No** to return to the previous menu.
- 7. Press Esc to return to the previous menu.

Creating Arrays

Before creating arrays, make sure the disks for the array are connected and installed in your system. Note that disks with no usable space, or disks that are un-initialized are shown in gray and cannot be used. See *Initializing Disk Drives*.

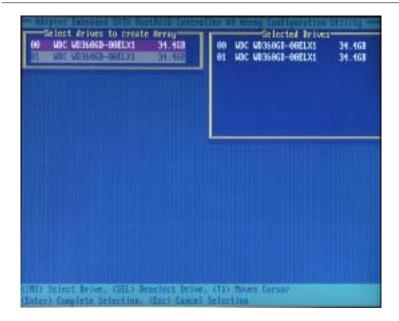
To create an array:

- 1 Turn on your computer and press Ctrl+A when prompted to access the ARC utility.
- 2 From the ARC menu, select Array Configuration Utility Main Menu (ACU) (as shown on the first screen on page B-5).
- 3 From the ACU menu, select Create Array.
- 4 Select the disks for the new array and press Insert (as the screen shown below).

(*Note: To deselect any disk, highlight the disk and press Delete.)



5 Press **Enter** when both disks for the new array are selected. The Array Properties menu displays (as the screen shown on the next page).



Assigning Array Properties

Once you've create a new array, you are ready to assign the properties to the array.

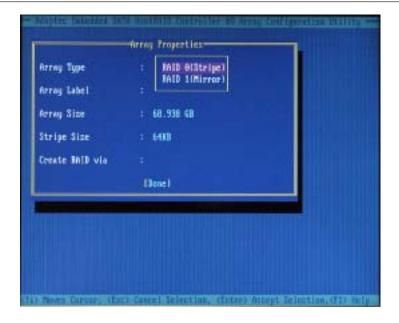
*Caution: Once the array is created and its properties are assigned, you cannot change the array properties using the ACU. You will need to use the Adaptec Storage Manager - Browser Edition. (Refer to Adaptec's User's Guide in the enclosed CD.)

To assign properties to the new array:

1. In the Array Properties menu (as shown in the following screen), select an array type and press **Enter**.

Note that only the available array types: RAID 0, and RAID1, are displayed on the screen. (*RAID 0 or RAID 1 requires two drives.)



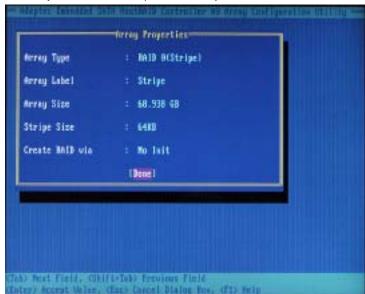


- 2. Under the item "Arrays Label", type in an label and press Enter. (*Note: The label shall not be more than 15 characters.)
- 3. For RAID 0, select the desired stripe size. (*Note: Available stripe sizes are 16, 32, and 64 KB-default. It is recommended that you do not change the default setting.)
- 4. The item: "Create RAID via" allows you to select between the different creating methods for RAID 0 and RAID 1.

The following table gives examples of when each is appropriate.

Raid Level	Create Via	When Appropriate
RAID 0	No Init	Creating a RAID 0 on new drives
RAID 0	Migrate	Creating a RAID 0 from one new drive and
	(*Note)	one drive with data you wish to preserve
RAID 1	Build1	Any time you wish to create a RAID 1, but especially if
		you have data on one drive that you wish to preserve
RAID 1	Clear	Creating a RAID 1 on new drives, or when you want to
		ensure that the array contains no data after creation.
RAID 1	Quick	Fastest way to create a RAID 1.
		Appropriate when using new drives
RAID 1	Init	

(*Note: If you select Migrate for RAID 0, or Build for RAID 1, you will be asked to select the source drive. The contents of the source drive will be preserved. However, the data on the new drive will be lost.)



5. When you are finished, press Done (as the screen shown below).

Notes:

- 1. Before adding a new drive to an array, back up any data contained on the new drive. Otherwise, all data will be lost.
- 2. If you stop the Build or Clear process on a RAID 1 from ACU, you can restart it by pressing Ctrl+R.
- 3. A RAID 1 created using the Quick Init option may return some data miscompares if you later run a consistency check. This is normal and is not a cause for concern.
- 4. The ACU allows you to use drives of different sizes in a RAID . However, during a build operation, only the smaller drive can be selected as the source or first drive.
- 5. When migrating from single volume to RAID 0, migrating from a larger drive to a smaller drive is allowed. However, the destination drive must be at least half the capacity of the source drive.
- 6. Adaptec does not recommend that you migrate or build an array on Windows dynamic disks (volumes), as it will result in data loss.

Warning: Do not interrupt the creation of a RAID 0 using the Migrate option. If you do, you will not be able to restart, or to recover the data that was on the source drive.

Adding a Bootable Array

To make an array bootable:

- 1. From the Main menu, select Manage Arrays.
- 2. From the List of Arrays, select the array you want to make bootable, and press Ctrl+B.
- 3. Enter Y to create a bootable array when the following message is displayed: "This will make all other existing bootable array non-bootable. Do you want to make this array bootable? (Yes/No):" Then, a bootable array will be created. An asterisk will appear next to the bootable array (as shown in the picture below:)



Deleting a Bootable Array

To delete a bootable array:

- 1. From the Main menu, select Manage Arrays.
- 2. From the List of Arrays, select the bootable array (*) you want to delete, and press Ctrl+B. (* a bootable array is the array marked with an asterisk (as shown in the picture above.)
- **3.** Enter Y to delete a bootable array when the following message is displayed: "The array is already marked bootable. Do you want to make this array as not bootable? (Yes/No):" Then, the bootable array will be deleted and the asterisk will disappear.

(*Note: do not use the delete key to delete the bootable array.)

Adding/Deleting Hotspares

(*Note: In order to rebuild a RAID (RAID 0 or RAID 1), you would need to add a new HDD as a hotspare.)

- 1. Turn on your computer and press Ctrl+A as prompted to access the ARC Utility.
- 2. From the ARC menu, select Array Configuration Utility (ACU).
- 3. From the ACU menu, select Add/Delete Hotspares.
- 4. Use the up and down arrow keys to highlight and select the disk you want to designate as a hotspare, and press <Insert>, and then, press <Enter>.
- 5. Press yes when the following prompt is displayed:

"Do you want to create spare?" (Yes/No?)

The spare you have selected will appear in the Select Drive Menu.

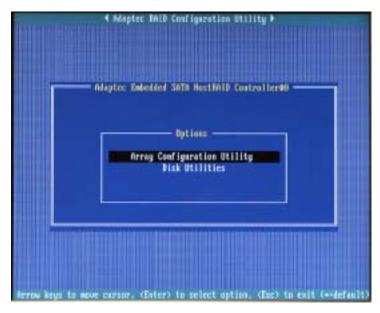
Initializing Disk Drives

If an installed disk does not appear in the disk selection list for creating a new array, or if it appears grayed out, you may have to initialize it before you can use it as part of an array. Drives attached to the controller must be initialized before they can be used in an array.

Caution: Initializing a disk overwrites the partition table on the disk and makes any data on the disk inaccessible. If the drive is used in an array, you may not be able to use the array again. **Do not** initialize a disk that is part of a boot array. To determine which disks are associated with a particular array, please refer to *Viewing Array Properties*.

To initialize drives:

- 1. Turn on your computer and press Ctrl+A when prompted to access the ARC utility.
- 2. From the ARC menu, select Array Configuration Utility (ACU) (as shown in the screen below).



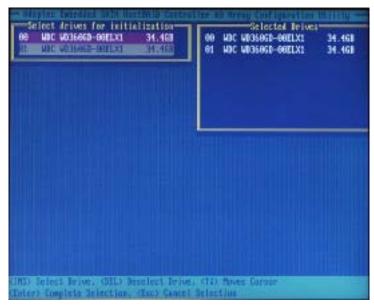
3. Select Initialize Drives (as shown in the screen below).



4. Use the up and down arrow keys to highlight the disk you wish to initialize and press **Insert** (as shown in the screen below).



5. Repeat Step 4 so that both drives to be initialized are selected (as shown in the screen below).



- 6. Press Enter.
- 7. Read the warning message as shown in the screen.



8. Make sure that you have selected the correct disk drives to initialize. If correct, type Y to continue.

Rebuilding Arrays

*Note 1: Rebuilding applies to Fault Tolerant array (RAID 1) only.

If an array Build process (or initialization) is interrupted or critical with one member missing, you must perform a Rebuild to optimized its functionality. For a critical array Rebuild operation, the optimal drive is the source drive.

*Note 2: If no spare array exists and a hard disk drive fails, you need to create a spare before you can rebuild an array.

To Rebuild an array:

- 1 From the Main Menu, select **Manage Arrays** (as shown in the screen below). From the List of Arrays, select the array you want to Rebuild.
- 2 Press Ctrl+R to Rebuild.

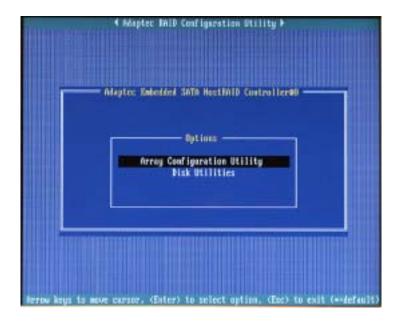


Using the Disk Utilities

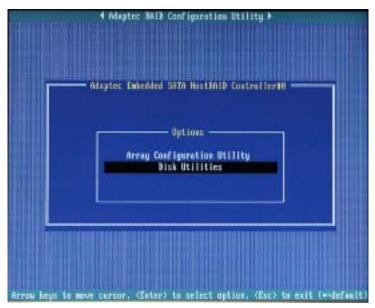
The Disk Utilities enable you to format or verify the media of your Serial ATA hard disks.

To access the disk utilities:

1. Turn on your computer and press Ctrl+A when prompted to access the ARC utility (as shown in the screen below.)



2. From the ARC menu, select **Disk Utilities** as shown in the screen below.



3 Select the desired disk and press **Enter** (as shown in the screen below.)



You can choose from the following options:

1. Format Disk—Simulates a low-level format of the hard drive by writing zeros to the entire disk. Serial ATA drives are low-level formatted at the factory and do not need to be low-level formatted again.

(*Caution: Formatting destroys all data on the drive. Be sure to back up your data before performing this operation.)

2. Verify Disk Media—Scans the media of a disk drive for defects.

To Exit Adaptec RAID Configuration Utility

- 1. Once you have completed RAID array configurations, press ESC to exit. The following screen will appear.
- 2. Press Yes to exit the Utility.



(*For more information regarding Adaptec RAID Utility, please refer to Adaptec's User's Guide in the CD included in your shipping package. You can also download a copy of Adaptec User's Guide from our web site at: www. supermicro.com.)

B-2 Installing Intel's ICH5R Driver by Adaptec and Windows Operating System

- a. Insert Supermicro's bootable CD that came with the package into the CD Drive during the system reboot, and the screen: "Super Micro Driver Diskette Maker" will appear.
- b. Choose from the list the item: "Intel ICH5R Driver by 3rd Party (Adaptec)" and press <ENTER>.
- c. From the next screen displayed, choose the OS driver you want to install and press <Enter>.
- d. Insert a formatted diskette into drive A: and press <Enter> as prompted.
- e. Exit the program after the process is completed. Then, reboot the system.
- f. Insert Microsoft Windows OS Setup CD in the CD Driver, and the system will start to boot up from CD.
- g. Press the <F6> key when the message-"Press F6 if you need to install a third party SCSI or RAID driver" displays.
- h. When the Windows OS Setup screen appears, press "S" to specify additional device(s).
- i. Insert the driver diskette-"Adaptec Embedded Serial ATA Raid Controller Driver" into Drive A: and press the <Enter> key.
- j. Choose Adaptec Embedded Host Serial ATA Raid Controller from the list indicated in the Windows OS Setup Screen, and press the <Enter> key.
- k. Press the <Enter> key to continue the installation process. (If you need to specify any additional devices to be installed, do it at this time.) Once all devices are specified, press the <Enter> key to continue with the installation.
- I. From the Windows OS Setup screen, press the <Enter> key. The OS Setup will automatically load all device files, and, then, continue the Windows OS installation.
- m. After Windows OS Installation is completed, the system will automatically reboot.

B-3 Installing Other Software Programs and Drivers

A. Installing Drivers other than Adaptec Embedded Serial ATA RAID Controller Driver

After you've installed Windows Operating System, a screen as shown below will appear. You are ready to install software programs and drivers that have not yet been installed. To install these software programs and drivers, click the icons to the right of these items.



Driver/Tool Installation Display Screen

(*Note: Click the icons showing a hand writing on paper to view the readme files for each item. Click the computer icons to the right of these items to install each item (from top to the bottom) one at a time. After installing each item, you must re-boot the system before moving on to the next item on the list. You should install everything here except for the SUPER Doctor utility, Intel LDCM and the LAN/SCSI driver diskettes, which are optional. The bottom icon with a CD on it allows you to view the entire contents of the CD.)

(*Please refer to the Adaptec User's Guide for the installation of Adaptec's Serial ATA RAID Controller Driver. Adaptec's User's Guide is included in the CD. You can also download a copy of the user's guide from our web site.)

Supero Doctor III

The Supero Doctor III program is a Web base management tool that supports remote management capability. It includes Remote and Local Management tools. The local management is called SD III Client. The Supero Doctor III program included on the CDROM that came with your motherboard allows you to monitor the environment and operations of your system. Supero Doctor III displays crucial system information such as CPU temperature, system voltages and fan status. See the Figure below for a display of the Supero Doctor III interface.

Supero Doctor III Interface Display Screen-I (Health Information)



Supero Doctor III Interface Display Screen-II (Remote Control)



(*Note: SD III Software Revision 1.0 can be downloaded from our Web site at: ftp://ftp.supermicro.com/utility/Supero_Doctor_III/. You can also download SDIII User's Guide at: http://www.supermicro.com/PRODUCT/Manuals/SDIII/UserGuide.pdf. For Linux, we will still recommend Supero Doctor II.)